

Last time.

Def of linear maps: a map $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is linear if

(1) $T(v+w) = T(v) + T(w)$ and (2) $T(cv) = cT(v) \quad \forall v, w \in \mathbb{R}^n$
and $c \in \mathbb{R}$.

Properties of linear maps: say $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is linear.

— (0 to 0) $T(\vec{0}) = \vec{0}$.

— (new from old) if $\underline{T(v_1), \dots, T(v_k)}$ are known, then $T(v)$ can be computed

$\forall v \in \text{Span}\{v_1, \dots, v_k\}: v = c_1 v_1 + \dots + c_k v_k \Rightarrow T(v) = T(c_1 v_1 + \dots + c_k v_k)$

— ("component") A map $S: \mathbb{R}^n \rightarrow \mathbb{R}^m, v \mapsto \begin{bmatrix} s_1(v) \\ \vdots \\ s_m(v) \end{bmatrix}$ is linear iff S_i is linear $\forall i$.
 $= c_1 \underline{T(v_1)} + \dots + c_k \underline{T(v_k)}$

Examples and formulas of linear maps:

$\begin{bmatrix} x \\ y \end{bmatrix} \begin{matrix} \nearrow \\ \searrow \end{matrix} \begin{matrix} \begin{bmatrix} x+y \\ 2x-3y \end{bmatrix} \checkmark \text{ linear.} \\ \begin{bmatrix} \sin x \\ x^2+y \end{bmatrix} \times \text{ not linear.} \end{matrix}$

Claim: A map $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is linear iff there is a matrix A s.t. $T(v) = A \cdot v \quad \forall v \in \mathbb{R}^n$.

Today: · proof of the claim

· notions associated to linear maps.

1. Linear maps \equiv matrix multiplication

eg. $m=3$
 $n=2$ $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 1 & 1 \end{bmatrix}$. $v = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$, $w = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$.
 $c = 5$.

Note that for any $m \times n$ matrix A and $v, w \in \mathbb{R}^n$ and $c \in \mathbb{R}$

we have (i) $A(v+w) = Av + Aw$ and (ii) $A(cw) = cAw$

Pf: Suppose $A = [a_{ij}]$ (ij th entry being a_{ij}) and $v = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$, $w = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$.

For (i), we note that $\forall 1 \leq j \leq m$,

$$\begin{aligned} [A(v+w)]_j &= \sum_{k=1}^n A_{jk} (v+w)_k = \sum_{k=1}^n A_{jk} (v_k + w_k) \\ &= \sum_{k=1}^n A_{jk} v_k + \sum_{k=1}^n A_{jk} w_k = [Av]_j + [Aw]_j = [Av + Aw]_j. \end{aligned}$$

so $A(v+w) = Av + Aw$. (ii) can be proved similarly.

Prop 1. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a map given by $T(x) = Ax$ where A is a matrix.
 $\forall x \in \mathbb{R}^n$

Then T is linear.

Pf: Let $v, w \in \mathbb{R}^n$, and let $c \in \mathbb{R}$.

$$(1) \quad T(v+w) = A(v+w) \stackrel{(i)}{=} Av + Aw = T(v) + T(w).$$

$$(2) \quad T(cv) = A(cv) \stackrel{(ii)}{=} cAv = cT(v).$$

By (1) and (2), T is linear. \square

Eg. Prove that the map $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x-y \\ 3x \end{bmatrix}$ is linear.

Pf: Note that $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x-y \\ 3x \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix}}_{\text{"A"}} \begin{bmatrix} x \\ y \end{bmatrix}$;

that is, T is mult by the matrix $\begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix}$,

so T is a linear map by Prop 1.

Thm 2. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. Then there exists a unique matrix

$$A_T \text{ s.t. } T(x) = A_T \cdot x \quad \forall x \in \mathbb{R}^n.$$

This unique matrix is

$$A_T = \left[T(e_1) \mid T(e_2) \mid \dots \mid T(e_n) \right]$$

where $\{e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, e_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}\}$ is the so-called standard basis

Def: The matrix A_T associated to the linear T is called the standard matrix of T .

e.g.: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2, \begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x-y \\ 3x \end{bmatrix}$

earlier observation:

$$\begin{bmatrix} 2x-y \\ 3x \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix}}_A \begin{bmatrix} x \\ y \end{bmatrix}$$

the theorem: $A_T = \left[T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) \mid T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \right] = \left[\begin{array}{c|c} 2 & -1 \\ 3 & 0 \end{array} \right],$
(deterministic)

Pf: Write $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$ for $\vec{x} \in \mathbb{R}^n$. Note that $\vec{x} = x_1 e_1 + \dots + x_n e_n$.

Since T is linear,

$$T(x) = T(x_1 e_1 + \dots + x_n e_n)$$

$$= x_1 \underbrace{T(e_1)}_{\in \mathbb{R}^m} + \dots + x_n \underbrace{T(e_n)}_{\in \mathbb{R}^m} \quad \text{by linearity}$$

$$= \begin{bmatrix} | & & | \\ T(e_1) & \dots & T(e_n) \\ | & & | \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad \text{by def of matrix-vector product}$$

$$= A_T \cdot \vec{x}$$

(uniqueness): **EX**.

□.

Remarks:

- Prop 1 and Thm 2 combine to prove our claim from last time.

" linear maps \equiv matrix multiplications".

In particular, if $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$, $T(v) = \begin{bmatrix} T_1(v) \\ \vdots \\ T_n(v) \end{bmatrix} \forall v \in \mathbb{R}^n$,

then T is linear iff each $T_i(v)$ is a lin. comb of the coordinates of v .

- Later, we will study linear maps via their standard matrices.

2. Image, Kernel, Injectivity and Surjectivity

Def. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map.

(1) The image of T is defined to be the set

$$\text{Im } T := \{ T(v) \mid v \in \mathbb{R}^n \}.$$

(2) The kernel of T is the set

$$\text{Ker } T := \{ v \in \mathbb{R}^n \mid T(v) = 0 \}.$$

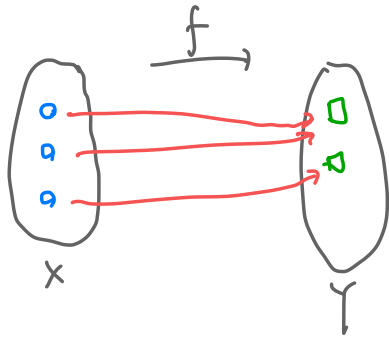
Note: Since $T(v) = A_T \cdot v \quad \forall v \in \mathbb{R}^n$ where A_T is the standard matrix,

$\text{ker } T$ is just the soln set of the hom eq. $A_T \cdot x = 0$.

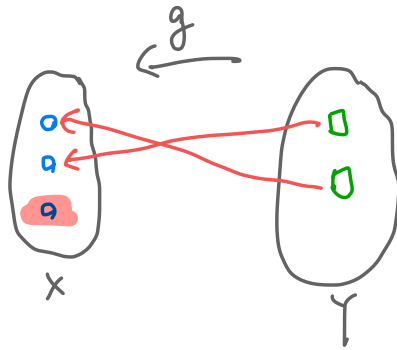
(3) We say T is surjective (surj.) or onto if every elt in \mathbb{R}^m is an output of T , i.e., if $\text{Im } T = \mathbb{R}^m$.

(4) We say T is injective (inj.) or one-to-one if every elt in \mathbb{R}^n is the output of at most one input, i.e., if " $T(v) = T(v')$ for $v, v' \in \mathbb{R}^n \Rightarrow v = v'$ ".

Note: By definition,



surj; not inj.



not surj; inj.

Eg. Consider the map $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x+y \\ 4x+y \end{bmatrix}$.

(0) Find the standard matrix of T .

(1) Find the image of T .

(2) Find the kernel of T (in parametrized vector form).

(3) Determine whether T is surj.

Next time:

• more examples.

• " T is inj $\Leftrightarrow \ker T = \{0\}$ "

• connecting surj/inj to span/lin. ind.

• geom maps in \mathbb{R}^2 & \mathbb{R}^3

EX: Try (0) - (4)