

Last time: - more diagonalization examples.

- Why $A = P D P^{-1}$ (with A $n \times n$): consider the map $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^n$, $x \mapsto Ax$ and its matrices w.r.t. the standard basis.

Today: examples, hw. discussions, and the eigenbasis.

Recall: Given a linear map $T: V \rightarrow W$, a basis β of V and a basis γ of W , the matrix of T $\{b_1, \dots, b_k\}$

w.r.t. β and γ is

$$[T]_{\beta}^{\gamma} = \begin{bmatrix} [T(b_1)]_{\gamma} & \dots & [T(b_k)]_{\gamma} \end{bmatrix}$$

Def: If $V=W$

and $\beta = \gamma$,

we write $[T]_{\beta} = [T]_{\beta}^{\beta}$ and call it the β -matrix of T .

E.g. 11) $A = \begin{bmatrix} 2 & 3 \\ 3 & -6 \end{bmatrix}$ (Lecture 35)

C : the standard basis

$\lambda_1 = -7 \rightarrow B_1 = \left\{ \underbrace{\begin{bmatrix} -1 \\ 3 \end{bmatrix}}_{v_1} \right\}$

$\lambda_2 = 3 \rightarrow B_2 = \left\{ \underbrace{\begin{bmatrix} 3 \\ 1 \end{bmatrix}}_{v_2} \right\}$

$\rightarrow B = \left\{ \begin{bmatrix} -1 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \end{bmatrix} \right\}$ is an eigenbasis for A

$\rightarrow P = \begin{bmatrix} -1 & 3 \\ 3 & 1 \end{bmatrix} = \underset{C \leftarrow B}{P}$

$T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2, v \mapsto Av.$

$T(v_1) = -7v_1,$

$T(v_2) = 3v_2,$ so

$[T]_B^B = \begin{bmatrix} [T(v_1)]_B & [T(v_2)]_B \end{bmatrix}$

$A = PDP^{-1}$

$= \begin{bmatrix} [-7v_1]_B & [3v_2]_B \end{bmatrix}$

$[T]_C^C = \underset{C \leftarrow B}{P} [T]_B^B \underset{B \leftarrow C}{P}$

$= \begin{bmatrix} -7 & 0 \\ 0 & 3 \end{bmatrix} = D.$

$$(2). \quad A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix} \quad (\text{Lec. 35.})$$

C : the standard basis
of \mathbb{R}^3 .

$$\lambda_1 = 1 \quad \rightarrow \quad B_1 = \left\{ \underbrace{\begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}}_{v_1} \right\}$$

$$\lambda_2 = -2 \quad \rightarrow \quad B_2 = \left\{ \underbrace{\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}}_{v_2}, \underbrace{\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}}_{v_3} \right\}$$

$$\left. \begin{array}{l} B_1 \\ B_2 \end{array} \right\} \rightarrow B = \{v_1, v_2, v_3\} \rightarrow P = [v_1 \ v_2 \ v_3] = \underset{C \leftarrow B}{P}$$

$$T_A: \mathbb{R}^3 \rightarrow \mathbb{R}^3, \quad v \mapsto Av$$

$$T_A(v_1) = 1 \cdot v_1, \quad T_A(v_2) = -2v_2, \quad T_A(v_3) = -2v_3 \quad \Rightarrow \quad [T]_B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix} = D$$

$$A = PDP^{-1} \quad \leftrightarrow \quad [T_A]_C = \underset{C \leftarrow B}{P} [T]_B \underset{B \leftarrow C}{P}$$

Upshot: To find a basis B s.t. $[T_A]_B^B$ is diagonal is the same as to find a diagonalization of the matrix A .

Eg. Ex 5.4.13. Consider $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $v \mapsto Av$ where

$$A = \begin{bmatrix} 0 & 1 \\ -3 & 4 \end{bmatrix}.$$

Find a basis B of \mathbb{R}^2 s.t. $[T]_B = [T]_B^B$ is diagonal.

Soln: $\text{char}_A(x) = \begin{vmatrix} 0-x & 1 \\ -3 & 4-x \end{vmatrix} = -x(4-x) + 3 = x^2 - 4x + 3$

$$= (x-1)(x-3)$$

eigenvalues: $\lambda_1 = 1$, $\lambda_2 = 3$, both w/ alg. mult = 1.

In particular, A is diagonalizable.

$$E_{\lambda_1} = \text{Null}(A - \lambda_1 I) = \text{Null} \begin{bmatrix} 0-1 & 1 \\ -3 & 4-1 \end{bmatrix} = \text{Null} \left(\begin{bmatrix} -1 & 1 \\ -3 & 3 \end{bmatrix} \right).$$

Since $\dim E_{\lambda_1} = 1$ and $v_1 := \begin{bmatrix} 1 \\ 1 \end{bmatrix} \in E_{\lambda_1}$, $B_1 = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ is a basis of E_{λ_1} .

$$E_{\lambda_2} = \text{Null}(A - \lambda_2 I) = \text{Null} \left(\begin{bmatrix} 0-3 & 1 \\ -3 & 4-3 \end{bmatrix} \right) = \text{Null} \left(\begin{bmatrix} -3 & 1 \\ -3 & 1 \end{bmatrix} \right).$$

Since $\dim E_{\lambda_2} = 1$ and $v_2 := \begin{bmatrix} 1 \\ 3 \end{bmatrix} \in E_{\lambda_2}$, $B_2 = \left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix} \right\}$ is a basis of E_{λ_2} .

It follows that for the basis $B = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \end{bmatrix} \right\}$ is a basis of \mathbb{R}^2

s.t. $[T]_B$ is diagonal (in fact, $[T]_B = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}$). \square

Ex 5.13.14 (Hw.)

$$A = \begin{bmatrix} 5 & -3 \\ -7 & 1 \end{bmatrix}, \quad T: \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad v \mapsto Av \quad \forall v \in \mathbb{R}^2.$$

Todo: find a basis B of \mathbb{R}^2 s.t. $[T]_B$ is diagonal.

- mimic the last problem; diagonalize A .

Ex. 5.4.17. Let $A = \begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix}$ and $B = \{b_1, b_2\}$ for

$b_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $b_2 = \begin{bmatrix} 5 \\ 4 \end{bmatrix}$. Define $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $x \mapsto Ax$.

(a). Verify that b_1 is an e-vec but A is not diag.

(b). Find the B -matrix of T .

Soln: (a). $Ab_1 = \begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} = 2b_1$,

so b_1 is an evec. with evalue 2.

$$\text{char}_A(x) = \begin{vmatrix} 1-x & 1 \\ 1 & 3-x \end{vmatrix} = (1-x)(3-x) + 1 = x^2 - 4x + 4 = (x-2)^2$$

so A has a unique evalue $\lambda = 2$ of alg. mult 2.

$$E_\lambda = \text{Null} \left(\begin{bmatrix} 1 & -2 \\ -1 & 3 \end{bmatrix} \right) = \text{Null} \left(\begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix} \right)$$

$$\begin{bmatrix} -1 & 1 & 0 \\ -1 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\rightarrow E_\lambda = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x - y = 0, y \in \mathbb{R} \right\} = \left\{ y \begin{bmatrix} 1 \\ 1 \end{bmatrix} : y \in \mathbb{R} \right\}.$$

So a basis of E_λ is $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ and $\text{geom. mult}(\lambda) = \dim E_\lambda = 1$.

Since $\text{geom. mult}(\lambda) < \text{alg. mult}(\lambda)$, A is not diagonalizable.

(b). (by (a), we shouldn't expect $[T]_{\mathcal{B}}$ to be diagonal.)

$$T(b_1) = 2b_1, \quad \text{so} \quad [T(b_1)]_{\mathcal{B}} = \begin{bmatrix} 2 \\ 0 \end{bmatrix},$$

$$T(b_2) = Ab_2 = \begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} 5 \\ 4 \end{bmatrix} = \begin{bmatrix} 9 \\ 7 \end{bmatrix} = ? \underbrace{\begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{b_1} + \underbrace{1?}_{?} \underbrace{\begin{bmatrix} 5 \\ 4 \end{bmatrix}}_{b_2}.$$

$$\begin{bmatrix} 1 & 5 & 9 \\ 1 & 4 & 7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 5 & 9 \\ 0 & -1 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 5 & 9 \\ 0 & 1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \end{bmatrix}$$

So $T(b_2) = -1b_1 + 2b_2$, hence $[T(b_2)]_{\mathcal{B}} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$.

It follows that

$$[T]_{\mathcal{B}} = \left[\begin{array}{c} [T(b_1)]_{\mathcal{B}} \\ [T(b_2)]_{\mathcal{B}} \end{array} \right] = \begin{bmatrix} 2 & -1 \\ 0 & 2 \end{bmatrix}.$$

indeed not \leftarrow drag,
as expected!

□