

Last time. (a) Examples and formulas of linear vs. non-linear maps

(b) Linear maps  $\equiv$  matrix multiplication ✓

- Today.
- making (b) precise, as a thm.
  - Some terminology for linear maps.
  - Some geometric linear maps on  $\mathbb{R}^2$ .

linear?

$$x \mapsto 3x - 4. \quad \times$$

$$\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} x^2 \\ y-x \\ 2x \end{bmatrix} \quad \times$$

$$\begin{bmatrix} x \\ y \\ 0 \end{bmatrix} \mapsto \begin{bmatrix} 2x+y \\ -x-y \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \quad \checkmark$$

# 1. Linear maps $\equiv$ matrix multiplication.

Thm. Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear map. Then there exists a unique  $m \times n$  matrix  $M$  st.  $T(\vec{v}) = A \cdot \vec{v}$ . In fact,  $A$  is the matrix

$$A = \begin{bmatrix} T(e_1) & T(e_2) & \cdots & T(e_n) \end{bmatrix} \text{ where } \{e_1, e_2, \dots, e_n\} \text{ is the standard basis of } \mathbb{R}^n.$$

Def. We call the matrix  $A$  the standard matrix of  $T$ .

e.g.  $T: \begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x+y \\ -x-y \end{bmatrix}$

Key Idea: We'll often study a linear map  $T$  via its standard matrix.

$$\begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$T(e_1) = T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$T(e_2) = T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

## 2. Image, Kernel, Injectivity and Surjectivity

Def. Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear map.

(1) The image of  $T$  is defined to be the set

$$\text{Im } T := \{ T(\vec{v}) \mid \vec{v} \in \mathbb{R}^n \} \subseteq \mathbb{R}^m.$$

(2) The kernel of  $T$  is the set

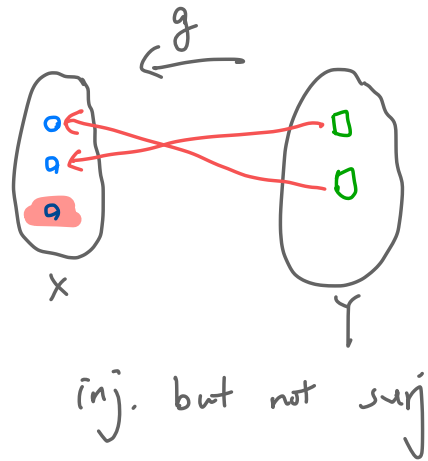
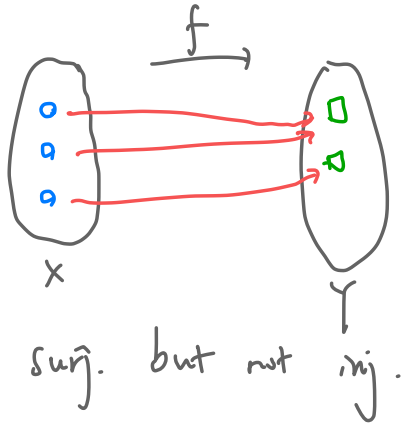
$$\text{Ker } T := \{ \vec{v} \in \mathbb{R}^n \mid T(\vec{v}) = \mathbf{0} \} \subseteq \mathbb{R}^n.$$

e.g.  $T: \mathbb{R}^2 \rightarrow \mathbb{R}$ .  $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto x-y$ .  $\text{ker } T = \{ \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} : x-y=0 \} = \{ \begin{bmatrix} y \\ y \end{bmatrix} : y \in \mathbb{R} \}$

e.g.  $S: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ ,  $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x+y \\ 4x+2y \end{bmatrix}$ . Ex:  $\begin{bmatrix} 1 \\ -2 \end{bmatrix} \in \text{Ker } T$ ,  $\begin{bmatrix} 1 \\ -3 \end{bmatrix} \notin \text{Ker } T$ .

(3) We say  $T$  is surjective if  $\text{Im } T = \mathbb{R}^m$ , i.e., if every elt in  $\mathbb{R}^m$  is the output of at least one input.

(4) We say  $T$  is injective if  $T(\vec{v}) = T(\vec{v}')$  for  $\vec{v}, \vec{v}' \in \mathbb{R}^n$  only when  $\vec{v} = \vec{v}'$ , i.e., every elt in  $\mathbb{R}^m$  is the output of at most one input.



An equivalent def of injectivity. Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear map.

Prop: The linear map  $T$  is injective iff  $\ker T = \{\vec{0}\}$ .

(So some people define an inj. linear map to be a linear map with kernel  $\{\vec{0}\}$ .)

Pf: "only if": Suppose  $T$  is inj. Take  $\vec{v} \in \ker T$ . Then  $T(\vec{v}) = \vec{0}$ .

On the other hand, we know that  $T(\vec{0}) = \vec{0}$ . So  $\vec{v} = \vec{0}$ . Therefore

$$\ker T = \{\vec{0}\}.$$

"if": Suppose  $\ker T = \{\vec{0}\}$ . Let  $\vec{v}, \vec{v}'$  be such that  $T(\vec{v}) = T(\vec{v}')$ .

Then  $T(\vec{v} - \vec{v}') = T(\vec{v}) - T(\vec{v}') = \vec{0}$ , so  $\vec{v} - \vec{v}' = \vec{0}$ , i.e.,  $\vec{v} = \vec{v}'$ .

Therefore  $T$  is inj.

## Some translations

Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear map and

let  $A$  be the standard matrix of  $T$ .

(a) (Image vs. Span Membership)

For a fixed  $\vec{w} \in \mathbb{R}^m$ , we have

$$\vec{w} \in \text{Im } T$$

$\Leftrightarrow \vec{w} \in \text{Span of the columns of } A$ .

before  
 $\Leftrightarrow$

EF  $\left( \left[ A \mid \vec{w} \right] \right)$  has no row of the form  $[0 \ 0 \ \dots \ 0 \ b]$   
where  $b \neq 0$ .

eg  $T: \begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x+y \\ x-y \\ 3y \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & 1 \\ 1 & -1 \\ 0 & 3 \end{bmatrix}}_A \begin{bmatrix} x \\ y \end{bmatrix}$

$$x \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} + y \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}$$

eg. Is  $\begin{bmatrix} 6 \\ 2 \\ 1 \end{bmatrix} \in \text{Im } T$ ?

Ex: Check  $\begin{bmatrix} 2 & 1 & \vdots & 6 \\ 1 & -1 & \vdots & 2 \\ 0 & 3 & \vdots & 1 \end{bmatrix}$ .

(b) (Surjectivity vs. spanning property)

We have

$T$  is surjective, i.e.,  $\text{Im } T = \mathbb{R}^m$

$\Leftrightarrow$  the columns of  $A$  span all of  $\mathbb{R}^m$

$\Leftrightarrow$   $\text{EF}(A)$  has no zero rows.

Ex.  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ ,  $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} x-y \\ 2x-2y \end{bmatrix}$ .

eg  $T: \begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x+y \\ x-y \\ 3y \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & 1 \\ 1 & -1 \\ 0 & 3 \end{bmatrix}}_A \begin{bmatrix} x \\ y \end{bmatrix}$

$$x \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} + y \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}$$

eg.

$$\mathbb{R}^m = \mathbb{R}^3$$

$\#$  cols of  $A = 2 < 3$ .

So the cols of  $A$

can't span  $\mathbb{R}^3$ .

So  $T$  can't be surj.

(c) (Injectivity vs. linear independence)

We have

$$\text{eg } T: \begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 2x+y \\ x-y \\ 3y \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & 1 \\ 1 & -1 \\ 0 & 3 \end{bmatrix}}_A \begin{bmatrix} x \\ y \end{bmatrix}$$

$T$  is inj. i.e.,  $\ker T = \{\vec{0}\}$

$\Leftrightarrow$  the only lin comb. of the cols of  $A$  that equals  $\vec{0}$  is the trivial one, i.e., the columns of  $A$  are linearly ind.

$\Leftrightarrow$   $\text{EF}(A)$  has a pivot in every column.

$$x \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} + y \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}$$

eg  $\begin{bmatrix} 2 & 1 \\ 1 & -1 \\ 0 & 3 \end{bmatrix}$

$$\rightarrow \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ 0 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 \\ 0 & 3 \\ 0 & 3 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & -1 \\ 0 & 3 \\ 0 & 0 \end{bmatrix}$$

all cols pivot E.x.  $\rightarrow T$  is inj.



Ex.  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ ,  $\begin{bmatrix} x \\ y \\ z \end{bmatrix} \mapsto \begin{bmatrix} x+2y \\ 3x+by \\ 0 \end{bmatrix}$ .

Is it surj / inj?

Size bounds for surjectivity/injectivity:

Ex. Using the equivalences on the previous two pages.

Show that if  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is linear, then

(1). if  $T$  is surj, then  $n \geq m$ .

(2). if  $T$  is inj, then  $n \leq m$ .