

Final Exam

Linear Algebra

MATH 2130

Spring 2021

Saturday May 1, 2021

NAME: _____

PRACTICE EXAM

Question:	1	2	3	4	5	6	Total
Points:	20	20	20	20	20	20	120
Score:							

- This exam is closed book.
- You may use only paper and pencil.
- You may not use any other resources whatsoever.
- You will be graded on the clarity of your exposition.

1. (20 points) • Let $K \in \{\mathbb{Q}, \mathbb{R}, \mathbb{C}\}$, let $V_1, V_2, V'_1,$ and V'_2 be K -vector spaces, and suppose that $L_1 : V_1 \rightarrow V'_1$ and $L_2 : V_2 \rightarrow V'_2$ are linear maps of K -vector spaces.

Recall that there is a so-called product linear map of K -vector spaces defined as follows on the products of the K -vector spaces:

$$L = L_1 \times L_2 : V_1 \times V_2 \longrightarrow V'_1 \times V'_2$$

$$L(v_1, v_2) = (L_1(v_1), L_2(v_2)).$$

If L_1 and L_2 are isomorphisms, show that L is also an isomorphism.

1
20 points

2. (20 points) • Let $\mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}$, $\mathbf{x}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{x}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$, and $\mathbf{x}_4 = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix}$.

Find an orthonormal basis for the vector subspace of \mathbb{R}^4 spanned by \mathbf{x}_1 , \mathbf{x}_2 , \mathbf{x}_3 , and \mathbf{x}_4 .

2

20 points

3. • Consider the following real matrix

$$A = \begin{pmatrix} 3 & -1 & 1 \\ -1 & 5 & -1 \\ 1 & -1 & 3 \end{pmatrix}$$

- (a) (4 points) Find the characteristic polynomial $p_A(t)$ of A .
- (b) (4 points) Find the eigenvalues of A .
- (c) (4 points) Find a basis for each eigenspace of A in \mathbb{R}^3 .
- (d) (4 points) Is A diagonalizable? If so, find a matrix $S \in M_{3 \times 3}(\mathbb{R})$ so that $S^{-1}AS$ is diagonal. If not, explain.
- (e) (4 points) Is A diagonalizable with orthogonal matrices? If so, find an orthogonal matrix $U \in M_{3 \times 3}(\mathbb{R})$ so that $U^T AU$ is diagonal. If not, explain.

3
20 points

4. (20 points) • Let \mathbb{P}_3 be the real vector space of polynomials of degree at most 3 (my notation for this vector space has been $\mathbb{R}[t]_3$, but I am using the textbook's notation here). A basis of \mathbb{P}_3 is given by the polynomials $1, t, t^2, t^3$.

We have seen that there is an inner product on \mathbb{P}_3 given by evaluation at $-2, -1, 1,$ and 2 . In other words, given polynomials $p(t), q(t) \in \mathbb{P}_3$, we define the inner product by the rule

$$\begin{aligned}(p(t), q(t)) &:= (p(-2), p(-1), p(1), p(2)) \cdot (q(-2), q(-1), q(1), q(2)) \\ &= p(-2)q(-2) + p(-1)q(-1) + p(1)q(1) + p(2)q(2).\end{aligned}$$

Let $p_1(t) = t$, and $p_2(t) = t^2$.

Find the best approximation to $p(t) = t^3$ by the polynomials in $\text{Span}\{p_1(t), p_2(t)\}$. In other words, find the polynomial $q(t)$ in the span of $p_1(t)$ and $p_2(t)$, that is closest to the polynomial $p(t)$ with respect to the given inner product on \mathbb{P}_3 .

4
20 points

5. (20 points) • Maximize the quadratic form

$$Q(x_1, x_2, x_3) = 3x_1^2 - 2x_1x_2 + 2x_1x_3 + 5x_2^2 - 2x_2x_3 + 3x_3^2$$

subject to the constraint that $x_1^2 + x_2^2 + x_3^2 = 1$. In other words, find the maximum of the given quadratic form restricted to the unit sphere $S^2 = \{(x_1, x_2, x_3) \in \mathbb{R}^3 : x_1^2 + x_2^2 + x_3^2 = 1\}$.

[Hint: Compare to the matrix in Problem 3.]

5

20 points

6. • **TRUE** or **FALSE**. You do **not** need to justify your answer.

(a) (2 points) If $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, then $|\mathbf{x} \cdot \mathbf{y}| \leq \|\mathbf{x}\| \|\mathbf{y}\|$.

(b) (2 points) Two vectors in \mathbb{R}^n are orthogonal if their dot product is zero.

(c) (2 points) If $W \subseteq \mathbb{R}^n$ is a vector subspace and W^\perp is the orthogonal complement, then $W \subseteq W^\perp$.

(d) (2 points) If $A \in M_{m \times n}(\mathbb{R})$ and $\mathbf{b} \in \mathbb{R}^m$, then a least squares solution to the equation $A\mathbf{x} = \mathbf{b}$ is a vector $\hat{\mathbf{x}} \in \mathbb{R}^n$ such that $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$.

(e) (2 points) For the real vector space $C^0([0, 1])$ consisting of continuous functions $f : [0, 1] \rightarrow \mathbb{R}$ on the closed interval $[0, 1]$, the rule

$$(f(t), g(t)) = \int_0^1 f(t)g(t) dt$$

defines an inner product on $C^0([0, 1])$.

(f) (2 points) If A is any real matrix, then the matrix $A^T A$ has non-negative eigenvalues.

(g) (2 points) Every real square matrix is diagonalizable with orthogonal matrices.

(h) (2 points) Given symmetric matrices A and B of the same size, then AB is a symmetric matrix.

(i) (2 points) Every quadratic form has a maximum value.

(j) (2 points) Let $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$. The angle θ between \mathbf{x} and \mathbf{y} satisfies $\cos \theta = \frac{\mathbf{x} \cdot \mathbf{y}}{\|\mathbf{x}\| \|\mathbf{y}\|}$.

6
20 points