## Deterministic and nondeterministic automata

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## Recall

### Definition

# A deterministic finite automaton (DFA) is a 5-tuple $M = (Q, \Sigma, \delta, s, F)$ with

- Q a finite set (states),
- Σ a finite set (input alphabet),
- $\delta: Q \times \Sigma \rightarrow Q$  the transition function,
- $s \in Q$  the start state,
- $F \subseteq Q$  the set of final/accepting states.

*M* accepts  $w \in \Sigma^*$  if  $\delta^*(s, w) \in F$  for the extension  $\delta^*$  of  $\delta$  to  $\Sigma^*$ .

$$L(M) := \{w \in \Sigma^* : M \text{ accepts } w\}$$

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is the language of M.

#### Example

Is there a DFA  $M_3$  such that  $L(M_3) = \{w \in \{0,1\}^* : 001 \text{ is a substring of } w\}?$  |dea: Scan w for 00|  $Slales: slack s \dots no performed of <math>00|$  seen yel  $q_0 \dots just seen 00$  $q_{001} \dots q_{001} \dots q_{001}$ 



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## Nondeterministic finite automata

- Deterministic: current state and input symbol uniquely determine next state
- **Nondeterministic:** several choices for next state
  - Interpretation: all possible transitions are done in parallel/the 'right' one is guessed.
  - Not a realistic model of computation but a useful theoretical device for its analysis.

### Definition

## A nondeterministic finite automaton with $\epsilon$ -transitions ( $\epsilon$ -NFA) is a 5-tuple ( $Q, \Sigma, \Delta, s, F$ ) like a DFA except that

 $\Delta \colon Q \times \Sigma \cup \{\epsilon\} \to P(Q) \qquad (P(Q) \dots \text{ power set of } Q)$ 

- Recall  $\epsilon$  is the empty word, not an element in  $\Sigma$ .
- $\epsilon$ -transitions allow the NFA to change from a state q to any state in  $\Delta(q, \epsilon)$  without input.
- Wlog, the sets T := Δ(q, a) for any a ∈ Σ ∪ {ε} are ε-closed (i.e. if t ∈ T, then also Δ(t, ε) ⊆ T).



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### Definition

# For an $\epsilon$ -NFA $N = (Q, \Sigma, \Delta, s, F)$ the extended transition function

$$\Delta^* \colon Q imes \Sigma^* o P(Q)$$

is defined inductively for  $q \in Q, w \in \Sigma^*, a \in \Sigma$  by

$$egin{array}{lll} \Delta^*(q,\epsilon) & := \Delta(q,\epsilon) \ \Delta^*(q,\mathit{wa}) & := igcup_{r\in\Delta^*(q,w)}\Delta(r,\mathit{a}) \end{array}$$

assuming all  $\Delta(q, \epsilon)$  and  $\Delta(r, a)$  are  $\epsilon$ -closed.

- N accepts w if Δ\*(s, w) ∩ F ≠ Ø (i.e. N accepts w iff ∃ some path from s to a state in F that is labelled by w).
- N rejects w otherwise.

The language of N is

$$L(N) := \{ w \in \Sigma^* : M \text{ accepts } w \}.$$

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### Note

Every DFA can be considered as ε-NFA with Δ(q, a) := {δ(q, a)} (singleton) and Δ(q, ε) := Ø.

Every language accepted by a DFA is also accepted by some *e*-NFA. What about the converse?

Theorem (Subset construction (Rabin, Scott 1959)) Let  $N = (Q, \Sigma, \Delta, s, F)$  be an  $\epsilon$ -NFA with all  $\Delta(q, a)$   $\epsilon$ -closed. Let  $M = (Q', \Sigma, \delta, s', F')$  be the DFA with  $\triangleright Q' := P(Q),$   $\triangleright \delta(R, a) := \bigcup_{q \in R} \Delta(q, a)$  for  $R \subseteq Q, a \in \Sigma,$   $\flat s' := \Delta(s, \epsilon),$   $\triangleright F' := \{R \in P(Q) : R \cap F \neq \emptyset\}.$ Then L(N) = L(M).

### Proof

First show for all  $w \in \Sigma^*$  that

$$\delta^*(s',w) = \Delta^*(s,w) \tag{(\dagger)}$$

by induction on 
$$|w|$$
.  
**Base case:** For  $w = \epsilon$ ,  
 $\delta^*(s', \epsilon) \stackrel{\star}{=} s' \stackrel{\iota}{=} \Delta(s, \epsilon) \stackrel{\iota}{=} \Delta^*(s, \epsilon)$ .  
**Induction hypothesis:** (†) holds for  $w \in \Sigma^*$  of length *n*.

Let  $a \in \Sigma$ . Then

$$\begin{split} \delta^*(s', wa) &= \delta\big(\,\delta^*(s', w), a\big) \\ &= \delta\big(\,\Delta^*(s, w), a\big) \\ &= \bigcup_{q \in \Delta^*(s, w)} \Delta(q, a) \\ &= \Delta^*(s, wa) \end{split}$$

by definition of  $\delta^*$ by induction hypothesis by definition of  $\delta$ by definition of  $\Delta^*$ 

Hence (†) is proved.

### Proof, continued

Note: *N* accepts *w* iff  $\Delta^*(s, w) \cap F \neq \emptyset$ iff  $\delta^*(s', w) \in F'$  by (†) and the definition of *F'* iff *M* accepts *w*.

### Note

The subset construction translates an NFA with |Q| states into a DFA with  $2^{|Q|}$  states. Often fewer suffice.

### Example, continued

Recall the  $\epsilon$ -NFA N with 3 states,  $L(N) = \{0^{\ell}1^m2^n : \ell, m, n \in \mathbb{N}\}$ . There is a DFA M with L(M) = L(N) and

Since the other subsets cannot be reached from the starting state  $\{a, b, c\}$ , they can be omitted.