

NP-completeness

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Recall

- ▶ P ... problems that can be **decided in polynomial time**
- ▶ NP ... problems that can be **verified in polynomial time**
- ▶ $P \subseteq NP \subseteq EXPTIME$

One of the Millenium Problems

Is $P = NP$?

Reductions

Definition

Let $A, B \in \Sigma^*$. A **polynomial time many-one reduction** from A to B is a function $f: \Sigma^* \rightarrow \Sigma^*$ that is **computable by a DTM in polynomial time** such that

$$\forall x \in \Sigma^* : x \in A \text{ iff } f(x) \in B.$$

If a polynomial time many-one reduction from A to B exists, we write $A \leq_m^p B$.

Note

Logspace reductions \leq_m^{\log} , etc., are defined analogously.
Since $L \subseteq P$, also $\leq_m^{\log} \subseteq \leq_m^p$.

Hard problems don't reduce to easy ones

Lemma

Let $A \leq_m^P B$.

1. If $B \in P$, then $A \in P$.
2. If $B \in NP$, then $A \in NP$.

Proof.

- ▶ Let f be a reduction from A to B that is computable in n^k time for some $k \in \mathbb{N}$.
- ▶ Then $|f(x)| \leq |x|^k$.
- ▶ Assume $B \in \text{DTIME}(n^\ell)$ for some $\ell \in \mathbb{N}$.
- ▶ Then $f(x) \in B$ can be decided in time $|f(x)|^\ell \leq |x|^{k\ell}$.
- ▶ Thus $x \in A$ is decidable in $O(n^{k\ell})$ time.



The hardest problems in NP

Definition

B is **NP-hard** (with respect to \leq_m^P) if for all $A \in \text{NP}$: $A \leq_m^P B$

B is **NP-complete** if B is NP-hard and $B \in \text{NP}$.

Note

1. If some NP-complete problem is in P, then $P = \text{NP}$.
2. If A is NP-complete and $A \leq_m^P B$ for some $B \in \text{NP}$ then B is NP-complete.

Question

How to define “complete in P”?

Satisfiability of Boolean formulas

Definition

- ▶ A **Boolean formula** Φ is formed from variables x_1, x_2, \dots and logical connectives $\wedge, \vee, ' (negation)$.
- ▶ Φ is **satisfiable** if Φ is true for some assignment of its variables to 0, 1 (false, true).
- ▶ $SAT := \{ \#(\Phi) : \Phi \text{ is a satisfiable Boolean formula} \}$

Example

$\Phi(x_1, x_2, x_3) = (x_1' \vee x_2') \wedge (x_2 \vee x_3)$ is satisfiable by e.g.

$x_1 \mapsto 0, x_2 \mapsto 0, x_3 \mapsto 1$

Cook-Levin Theorem (1971)

SAT is NP-complete.

Proof.

SAT \in NP: If a satisfying assignment for Φ exists, it can be verified in polynomial time in $|\Phi|$.

Idea for hardness: For each $A \in$ NP construct a polytime reduction to SAT realizing the following correspondences:

- ▶ NP machine N on w \leftrightarrow Boolean formula Φ
- ▶ accepting computational path for w \leftrightarrow satisfying assignment

Let $A \in \text{NP}$ be decided by a nondeterministic TM N in time n^k for some $k \in \mathbb{N}$.

Wlog N deletes its tape and moves to position 0 before halting.

Represent a computational path of N for input w of length n by the following $n^k \times (n^k + 3)$ table T of configurations with entries in $C := Q \cup \Gamma \cup \{\#\}$ (state is left of the cell with the tape head):

| | | | |
|----------------------------|---------|-------------|------------------------|
| $\#s w_1 \dots w_n \sqcup$ | \dots | $\sqcup \#$ | start configuration |
| $\#$ | | $\#$ | 2nd configuration |
| \vdots | | | \vdots |
| $\#$ | | $\#$ | n^k th configuration |

- ▶ Describe T by a Boolean formula Φ in variables x_{iju} for $1 \leq i \leq n^k$, $1 \leq j \leq n^k + 3$, $u \in C$.
- ▶ Interpret $x_{iju} = \begin{cases} 1 & \text{if } T_{i,j} = u, \\ 0 & \text{else.} \end{cases}$

Define

$$\Phi := \Phi_{\text{cell}} \wedge \Phi_{\text{start}} \wedge \Phi_{\text{move}} \wedge \Phi_{\text{accept}}$$

such that Φ is satisfiable iff it describes an accepting computational path.

1. Each cell of T contains exactly one symbol from C :

$$\Phi_{\text{cell}} := \bigwedge_{i,j} \left(\left(\bigvee_{u \in C} x_{iju} \right) \wedge \bigwedge_{u \neq v} (x_{iju} \wedge x_{ijv})' \right)$$

2. The first row contains the start configuration:

$$\Phi_{\text{start}} := x_{11\#} \wedge x_{12s} \wedge x_{13w_1} \wedge \dots$$

3. The accept state t of N occurs in T :

$$\Phi_{\text{accept}} := x_{n^k 2t}$$

4. Φ_{move} expresses that each row encodes the successor configuration of the previous.

To define Φ_{move} say a 2×3 subblock of T is **legal** if it is consistent with the transition function Δ of N (or copying a halting configuration).

E.g. if $\Delta(q, a) = \{(q', b, -1), \dots\}$, the following are legal:

| | | |
|------|-----|-----|
| c | q | a |
| q' | c | b |

| | | |
|-----|-----|-----|
| q | a | d |
| c | b | d |

| | | |
|-----|-----|-----|
| a | b | c |
| a | b | c |

| | | |
|------|-----|----------|
| $\#$ | t | \sqcup |
| $\#$ | t | \sqcup |

These are illegal:

| | | |
|-----|-----|-----|
| a | b | b |
| a | a | b |

| | | |
|-----|-----|------|
| $*$ | $*$ | $*$ |
| q | $*$ | q' |

| | | |
|-----|-----|-----|
| c | q | a |
| a | c | b |

Let

$\Phi_{\text{move}} :=$ all 2×3 subblocks of T are legal

$$= \bigwedge_{i,j} \bigvee_{\substack{\begin{array}{|c|c|c|} \hline c_1 & c_2 & c_3 \\ \hline c_4 & c_5 & c_6 \\ \hline \end{array} \text{ legal}}} \left(\begin{array}{l} x_{i,j,c_1} \wedge x_{i,j+1,c_2} \wedge x_{i,j+2,c_3} \wedge \\ x_{i+1,j,c_4} \wedge x_{i+1,j+1,c_5} \wedge x_{i+1,j+2,c_6} \end{array} \right)$$

Claim.

If the top row of T represents the starting configuration of N and each 2×3 subblock is legal, then each row is the successor configuration of the previous (or the copy of the previous halting configuration)

Proof by induction on the rows of T .

- ▶ If a cell of T contains some $a \in \Gamma$ but is not next to a state, it is the center top of some legal 2×3 subblock

| | | |
|---|-----|---|
| * | a | * |
| * | a | * |

and remains unchanged.

- ▶ Cells next to some state $q \in Q \setminus \{r, t\}$ occur in legal blocks

| | | |
|---|-----|-----|
| * | q | a |
| * | * | * |

| | | |
|---|-----|----------|
| # | r | \sqcup |
| # | r | \sqcup |

| | | |
|---|-----|----------|
| # | t | \sqcup |
| # | t | \sqcup |

and change according to the transition function Δ .

This completes the proof that

$w \in L(N)$ iff $\Phi = \Phi_{\text{cell}} \wedge \Phi_{\text{start}} \wedge \Phi_{\text{move}} \wedge \Phi_{\text{accept}}$ is satisfiable.

Complexity of the reduction.

- ▶ Each variable is represented by its index in $O(\log n)$ space.
- ▶ Φ_{cell} is a conjunction of $O(n^{2k})$ formulas of fixed length.
- ▶ Φ_{start} is a conjunction of $O(n^k)$ variables.
- ▶ Φ_{move} is a conjunction of $O(n^{2k})$ formulas of fixed length.
- ▶ Φ_{accept} is a variable.

Since every part of Φ can be written down in polynomial time in n , we have $L(N) \leq_m^P \text{SAT}$. □

kSAT

A Boolean formula Φ is in k CNF if Φ is in conjunctive normal form and each clause has k literals (arguments or their negations), e.g. $\Phi = (x_1 \vee x_2' \vee x_3') \wedge (x_2 \vee x_3' \vee x_4)$ is in 3CNF.

$$k\text{SAT} := \{\Phi \text{ in } k\text{CNF} : \Phi \text{ is satisfiable}\}$$

Corollary

3SAT is NP-complete.

Proof.

Φ in the proof for SAT is a conjunction of Boolean formulas $\varphi(y_1, \dots, y_\ell)$ for a constant k .

1. Any $\varphi(y_1, \dots, y_k)$ can be written in k CNF with $\leq 2^k$ -clauses.
2. Any formula in k CNF can be written in 3CNF, e.g.

$y_1 \vee y_2' \vee y_3' \vee y_4$ is satisfiable iff
 $(y_1 \vee y_2' \vee z) \wedge (y_3' \vee y_4 \vee z')$ is satisfiable.

