

Every (f.g.) vector space has a basis

Finitely generated spaces

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.
- (2) Any independent subset can be enlarged to a basis.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.
- (2) Any independent subset can be enlarged to a basis.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.
- (2) Any independent subset can be enlarged to a basis.
- (3) All bases have the same cardinality.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.
- (2) Any independent subset can be enlarged to a basis.
- (3) All bases have the same cardinality.

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.
- (2) Any independent subset can be enlarged to a basis.
- (3) All bases have the same cardinality.
(This cardinality is called the **dimension** of \mathbb{V} , written $\dim(\mathbb{V})$.)

Finitely generated spaces

Definition. A subset $G \subseteq \mathbb{V}$ **generates** \mathbb{V} if $\mathbb{V} = \text{span}(G)$. \mathbb{V} is finitely generated if it has a finite spanning set.

In these slides we explained why, if \mathbb{V} is a finitely generated vector space,

- (1) Any spanning subset contains a basis.
- (2) Any independent subset can be enlarged to a basis.
- (3) All bases have the same cardinality.

(This cardinality is called the **dimension** of \mathbb{V} , written $\dim(\mathbb{V})$.)

(The same is true even if \mathbb{V} is not finitely generated, but the proof in the non-finitely generated case requires some background from set theory.)

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem.

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others.

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof:

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof: Assume that $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}$ is nontrivial because some $c_i \neq 0$.

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof: Assume that $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}$ is nontrivial because some $c_i \neq 0$. Solve for \mathbf{v}_i :

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof: Assume that $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}$ is nontrivial because some $c_i \neq 0$. Solve for \mathbf{v}_i :

$$\mathbf{v}_i = -(c_1/c_i)\mathbf{v}_1 - \cdots - \widehat{i\text{th term}} \cdots - (c_n/c_i)\mathbf{v}_n,$$

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof: Assume that $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}$ is nontrivial because some $c_i \neq 0$. Solve for \mathbf{v}_i :

$$\mathbf{v}_i = -(c_1/c_i)\mathbf{v}_1 - \cdots - \widehat{i\text{th term}} \cdots - (c_n/c_i)\mathbf{v}_n,$$

so \mathbf{v}_i is a linear combination of vectors in $G - \{\mathbf{v}_i\}$.

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof: Assume that $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}$ is nontrivial because some $c_i \neq 0$. Solve for \mathbf{v}_i :

$$\mathbf{v}_i = -(c_1/c_i)\mathbf{v}_1 - \cdots - \widehat{i\text{th term}} \cdots - (c_n/c_i)\mathbf{v}_n,$$

so \mathbf{v}_i is a linear combination of vectors in $G - \{\mathbf{v}_i\}$.

Conversely, if $\mathbf{v} \in G$ and $\mathbf{v} = c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n$, expresses \mathbf{v} as a linear combination of vectors in $G - \{\mathbf{v}\}$,

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof: Assume that $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}$ is nontrivial because some $c_i \neq 0$. Solve for \mathbf{v}_i :

$$\mathbf{v}_i = -(c_1/c_i)\mathbf{v}_1 - \cdots - \widehat{i\text{th term}} \cdots - (c_n/c_i)\mathbf{v}_n,$$

so \mathbf{v}_i is a linear combination of vectors in $G - \{\mathbf{v}_i\}$.

Conversely, if $\mathbf{v} \in G$ and $\mathbf{v} = c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n$, expresses \mathbf{v} as a linear combination of vectors in $G - \{\mathbf{v}\}$, then $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n - 1 \cdot \mathbf{v} = \mathbf{0}$ is a nontrivial dependence relation among elements of G .

Dependence

Definition. A **dependence relation** among a set G of vectors is a linear combination equal to the zero vector:

$$c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}.$$

The dependence relation is **trivial** if $c_1 = \cdots = c_n = 0$, and **nontrivial** otherwise.

Fact/Theorem. G satisfies a nontrivial dependence relation if and only if some vector in G is a linear combination of the others. (Note: $A \Leftrightarrow B$ is equivalent to $\neg A \Leftrightarrow \neg B$.)

Reason/Proof: Assume that $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n = \mathbf{0}$ is nontrivial because some $c_i \neq 0$. Solve for \mathbf{v}_i :

$$\mathbf{v}_i = -(c_1/c_i)\mathbf{v}_1 - \cdots - \widehat{i\text{th term}} \cdots - (c_n/c_i)\mathbf{v}_n,$$

so \mathbf{v}_i is a linear combination of vectors in $G - \{\mathbf{v}_i\}$.

Conversely, if $\mathbf{v} \in G$ and $\mathbf{v} = c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n$, expresses \mathbf{v} as a linear combination of vectors in $G - \{\mathbf{v}\}$, then $c_1 \cdot \mathbf{v}_1 + \cdots + c_n \cdot \mathbf{v}_n - 1 \cdot \mathbf{v} = \mathbf{0}$ is a nontrivial dependence relation among elements of G . \square

Dependence, 2

Definition.

Definition. Let \mathbb{V} be a vector space.

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$.

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$. (This means that $G \cup \{\mathbf{v}\}$ satisfies a dependence relation “involving” \mathbf{v} ; i.e., a dependence relation where the coefficient of \mathbf{v} is nonzero.)

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$. (This means that $G \cup \{\mathbf{v}\}$ satisfies a dependence relation “involving” \mathbf{v} ; i.e., a dependence relation where the coefficient of \mathbf{v} is nonzero.)

A subset $H \subseteq \mathbb{V}$ *depends* on G if every vector in H depends on G .

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$. (This means that $G \cup \{\mathbf{v}\}$ satisfies a dependence relation “involving” \mathbf{v} ; i.e., a dependence relation where the coefficient of \mathbf{v} is nonzero.)

A subset $H \subseteq \mathbb{V}$ *depends* on G if every vector in H depends on G . (This means that $H \subseteq \text{span}(G)$, which can be shown to be equivalent to $\text{span}(H) \subseteq \text{span}(G)$.)

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$. (This means that $G \cup \{\mathbf{v}\}$ satisfies a dependence relation “involving” \mathbf{v} ; i.e., a dependence relation where the coefficient of \mathbf{v} is nonzero.)

A subset $H \subseteq \mathbb{V}$ *depends* on G if every vector in H depends on G . (This means that $H \subseteq \text{span}(G)$, which can be shown to be equivalent to $\text{span}(H) \subseteq \text{span}(G)$.)

If \mathbf{v} does not depend on G , we say \mathbf{v} is **independent** of G .

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$. (This means that $G \cup \{\mathbf{v}\}$ satisfies a dependence relation “involving” \mathbf{v} ; i.e., a dependence relation where the coefficient of \mathbf{v} is nonzero.)

A subset $H \subseteq \mathbb{V}$ *depends* on G if every vector in H depends on G . (This means that $H \subseteq \text{span}(G)$, which can be shown to be equivalent to $\text{span}(H) \subseteq \text{span}(G)$.)

If \mathbf{v} does not depend on G , we say \mathbf{v} is **independent** of G .

- ① G is an independent set of vectors if and only if any $\mathbf{v} \in G$ is independent of $G - \{\mathbf{v}\}$.

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$. (This means that $G \cup \{\mathbf{v}\}$ satisfies a dependence relation “involving” \mathbf{v} ; i.e., a dependence relation where the coefficient of \mathbf{v} is nonzero.)

A subset $H \subseteq \mathbb{V}$ *depends* on G if every vector in H depends on G . (This means that $H \subseteq \text{span}(G)$, which can be shown to be equivalent to $\text{span}(H) \subseteq \text{span}(G)$.)

If \mathbf{v} does not depend on G , we say \mathbf{v} is **independent** of G .

- 1 G is an independent set of vectors if and only if any $\mathbf{v} \in G$ is independent of $G - \{\mathbf{v}\}$.
- 2 \mathbf{v} depends on G if and only if $\text{span}(G \cup \{\mathbf{v}\}) = \text{span}(G)$.

Definition. Let \mathbb{V} be a vector space. A vector $\mathbf{v} \in \mathbb{V}$ **depends** on a subset $G \subseteq \mathbb{V}$ if $\mathbf{v} \in \text{span}(G)$. (This means that $G \cup \{\mathbf{v}\}$ satisfies a dependence relation “involving” \mathbf{v} ; i.e., a dependence relation where the coefficient of \mathbf{v} is nonzero.)

A subset $H \subseteq \mathbb{V}$ *depends* on G if every vector in H depends on G . (This means that $H \subseteq \text{span}(G)$, which can be shown to be equivalent to $\text{span}(H) \subseteq \text{span}(G)$.)

If \mathbf{v} does not depend on G , we say \mathbf{v} is **independent** of G .

- 1 G is an independent set of vectors if and only if any $\mathbf{v} \in G$ is independent of $G - \{\mathbf{v}\}$.
- 2 \mathbf{v} depends on G if and only if $\text{span}(G \cup \{\mathbf{v}\}) = \text{span}(G)$.
- 3 If H depends on G and G depends on F , then H depends on F .

Any (finite) spanning set contains a basis

Any (finite) spanning set contains a basis

Theorem.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k ,

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k ,

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

- ① Each I_k is independent.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

- ① Each I_k is independent.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

- ① Each I_k is independent.
- ② $\text{span}(I_k) = \text{span}(\{\mathbf{v}_1, \dots, \mathbf{v}_k\})$.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

- ① Each I_k is independent.
- ② $\text{span}(I_k) = \text{span}(\{\mathbf{v}_1, \dots, \mathbf{v}_k\})$.

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

- ① Each I_k is independent.
- ② $\text{span}(I_k) = \text{span}(\{\mathbf{v}_1, \dots, \mathbf{v}_k\})$.
- ③ $I := I_n$ is an independent subset of G that spans the same subspace as G .

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

- ① Each I_k is independent.
- ② $\text{span}(I_k) = \text{span}(\{\mathbf{v}_1, \dots, \mathbf{v}_k\})$.
- ③ $I := I_n$ is an independent subset of G that spans the same subspace as G .

Any (finite) spanning set contains a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite, then there is an independent subset $I \subseteq G$ such that $\text{span}(I) = \text{span}(G)$.

Proof. Enumerate G as $\mathbf{v}_1, \dots, \mathbf{v}_n$. Recursively construct sets I_k by

- ① $I_0 = \emptyset$, and
- ② $I_{k+1} = I_k \cup \{\mathbf{v}_{k+1}\}$ if \mathbf{v}_{k+1} is independent of I_k , while $I_{k+1} = I_k$ if \mathbf{v}_{k+1} depends on I_k .

To verify:

- ① Each I_k is independent.
 - ② $\text{span}(I_k) = \text{span}(\{\mathbf{v}_1, \dots, \mathbf{v}_k\})$.
 - ③ $I := I_n$ is an independent subset of G that spans the same subspace as G .
-

Any independent subset can be enlarged to a basis

Any independent subset can be enlarged to a basis

Theorem.

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent,

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent, then there is an independent subset S

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent, then there is an independent subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$.

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent, then there is an independent subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$.

Proof.

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent, then there is an independent subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$.

Proof. Enumerate G with the elements of I enumerated first:

$$\underbrace{\mathbf{v}_1, \dots, \mathbf{v}_k}_{\in I}, \underbrace{\mathbf{v}_{k+1}, \dots, \mathbf{v}_n}_{\notin I}.$$

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent, then there is an independent subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$.

Proof. Enumerate G with the elements of I enumerated first:

$$\underbrace{\mathbf{v}_1, \dots, \mathbf{v}_k}_{\in I}, \underbrace{\mathbf{v}_{k+1}, \dots, \mathbf{v}_n}_{\notin I}.$$

Repeat the procedure of the last proof.

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent, then there is an independent subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$.

Proof. Enumerate G with the elements of I enumerated first:

$$\underbrace{\mathbf{v}_1, \dots, \mathbf{v}_k}_{\in I}, \underbrace{\mathbf{v}_{k+1}, \dots, \mathbf{v}_n}_{\notin I}.$$

Repeat the procedure of the last proof. You will end with a subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$.

Any independent subset can be enlarged to a basis

Theorem. If $G \subseteq \mathbb{V}$ is finite and $I \subseteq G$ is independent, then there is an independent subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$.

Proof. Enumerate G with the elements of I enumerated first:

$$\underbrace{\mathbf{v}_1, \dots, \mathbf{v}_k}_{\in I}, \underbrace{\mathbf{v}_{k+1}, \dots, \mathbf{v}_n}_{\notin I}.$$

Repeat the procedure of the last proof. You will end with a subset S satisfying $I \subseteq S \subseteq G$ and $\text{span}(S) = \text{span}(G)$. \square

All bases have the same cardinality

All bases have the same cardinality

Steinitz Exchange Lemma.

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} .

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

① $m \leq n$.

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

① $m \leq n$.

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

- 1 $m \leq n$.
- 2 After possibly reordering S , $\{\mathbf{u}_1, \dots, \mathbf{u}_m, \mathbf{v}_{m+1}, \dots, \mathbf{v}_n\}$ spans \mathbb{V} .

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

- 1 $m \leq n$.
- 2 After possibly reordering S , $\{\mathbf{u}_1, \dots, \mathbf{u}_m, \mathbf{v}_{m+1}, \dots, \mathbf{v}_n\}$ spans \mathbb{V} .

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

- 1 $m \leq n$.
- 2 After possibly reordering S , $\{\mathbf{u}_1, \dots, \mathbf{u}_m, \mathbf{v}_{m+1}, \dots, \mathbf{v}_n\}$ spans \mathbb{V} .

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

- 1 $m \leq n$.
- 2 After possibly reordering S , $\{\mathbf{u}_1, \dots, \mathbf{u}_m, \mathbf{v}_{m+1}, \dots, \mathbf{v}_n\}$ spans \mathbb{V} .

Corollary.

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

- 1 $m \leq n$.
- 2 After possibly reordering S , $\{\mathbf{u}_1, \dots, \mathbf{u}_m, \mathbf{v}_{m+1}, \dots, \mathbf{v}_n\}$ spans \mathbb{V} .

Corollary. If \mathbb{V} is finitely generated, then \mathbb{V} has a finite basis and all bases have the same cardinality, say d .

All bases have the same cardinality

Steinitz Exchange Lemma. Assume that $I = \{\mathbf{u}_1, \dots, \mathbf{u}_m\} \subseteq \mathbb{V}$, is independent and $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subseteq \mathbb{V}$ spans \mathbb{V} . Then

- 1 $m \leq n$.
- 2 After possibly reordering S , $\{\mathbf{u}_1, \dots, \mathbf{u}_m, \mathbf{v}_{m+1}, \dots, \mathbf{v}_n\}$ spans \mathbb{V} .

Corollary. If \mathbb{V} is finitely generated, then \mathbb{V} has a finite basis and all bases have the same cardinality, say d . All independent subsets of \mathbb{V} have size at most d , and all spanning subsets of \mathbb{V} have size at least d .