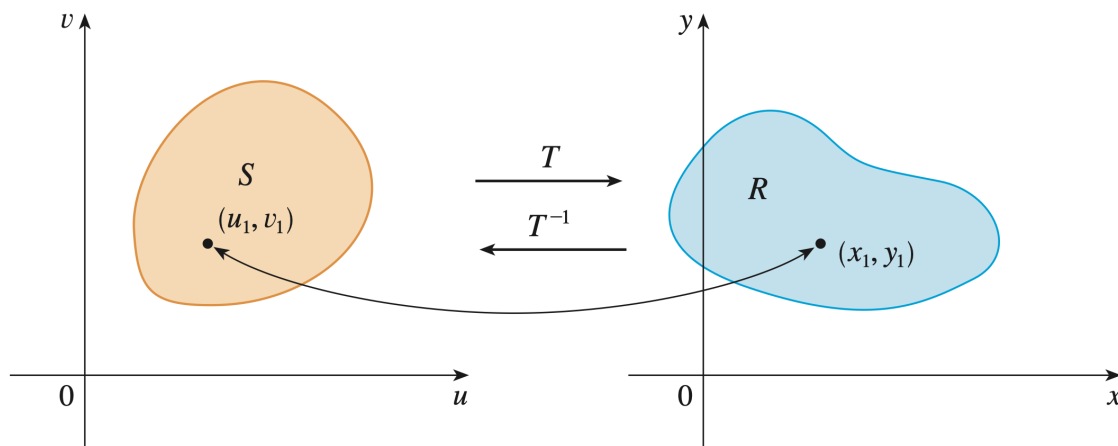


## 12.9 Change of Variables in Multiple Integrals

**Definition.** What is a transformation  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ ?

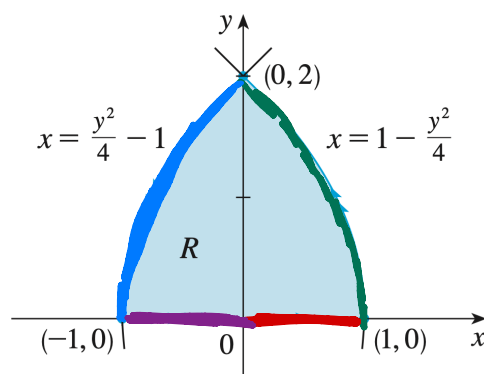
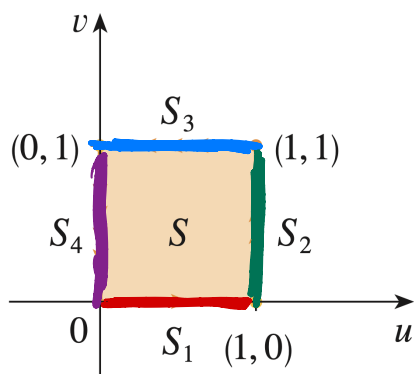


- A transformation  $T$  is a function whose domain and range are both subsets of  $\mathbb{R}^2$ .
- $T(u, v) = (x, y)$  where  $x = g(u, v)$  and  $y = h(u, v)$
- If no two points have the same image,  $T$  is called one-to-one (or injective). If  $T$  is one-to-one, then it has an inverse  $T^{-1}$ .
- We will usually assume that  $T$  is a  $C^1$  transformation. This means that  $g$  and  $h$  have continuous first order partial derivatives.

**Example.** A transformation is defined by the equations

$$x = u^2 - v^2, \quad y = 2uv$$

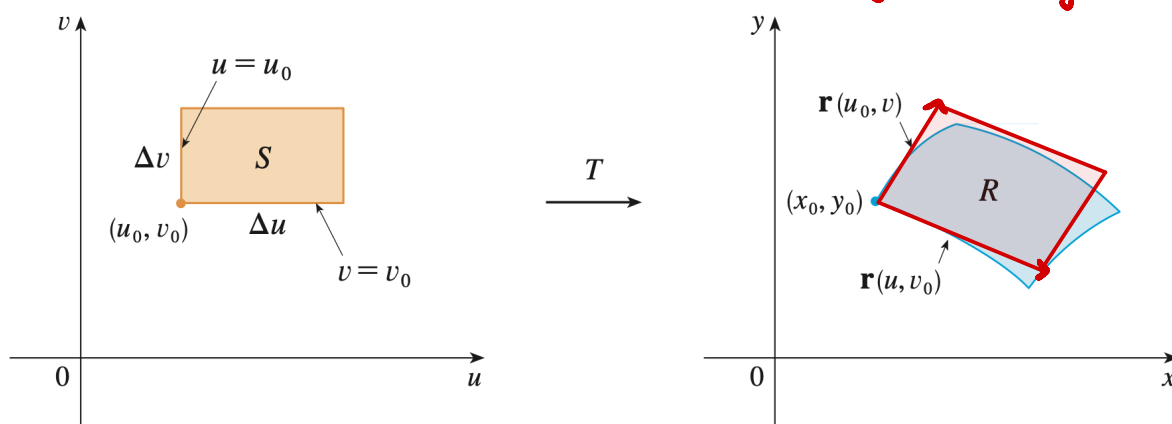
Find the image of the square  $S = [0, 1] \times [0, 1]$ .



- The side  $S_1$  is given by  $v=0$  ( $0 \leq u \leq 1$ )  
 $\Rightarrow x = u^2$  and  $y = 0$   
 $\Rightarrow S_1$  is mapped to the line segment from  $(0,0)$  to  $(1,0)$
- The side  $S_2$  is given by  $u=1$  ( $0 \leq v \leq 1$ )  
 $\Rightarrow x = 1 - v^2$  and  $y = 2v$   
 $\Rightarrow$  Eliminating  $v$ ,  $x = 1 - \frac{y^2}{4}$  for  $0 \leq y \leq 2$
- The side  $S_3$  is given by  $v=1$  ( $0 \leq u \leq 1$ )  
 $\Rightarrow x = u^2 - 1$  and  $y = 2u$   
 $\Rightarrow$  Eliminating  $u$ ,  $x = \frac{y^2}{4} - 1$  for  $0 \leq y \leq 2$
- The side  $S_4$  is given by  $u=0$  ( $0 \leq v \leq 1$ )  
 $\Rightarrow x = -v^2$  and  $y = 0$   
 $\Rightarrow S_4$  is mapped to the line segment from  $(-1,0)$  to  $(0,0)$

**Question.** Suppose that a rectangle  $S$  in the  $uv$ -plane is mapped to a region  $R$  in the  $xy$ -plane under a transformation  $T$ . If  $S$  has dimensions  $\Delta u$  and  $\Delta v$ , how can we approximate the area of the region  $R$ ?

Let  $T(u,v) = (x,y)$ , where  $x = g(u,v)$  and  $y = h(u,v)$



- Idea: Approximate  $R$  by a parallelogram. What are the sides?
- Given a point  $(u,v)$ ,  $\vec{r}(u,v) = \langle g(u,v), h(u,v) \rangle$  is the position vector of the image of  $(u,v)$  under  $T$ .
- At  $(x_0, y_0)$ , the tangent vectors are

$$\vec{r}_u = \langle g_u(u_0, v_0), h_u(u_0, v_0) \rangle = \left\langle \frac{\partial x}{\partial u}(u_0, v_0), \frac{\partial y}{\partial u}(u_0, v_0) \right\rangle$$

$$\vec{r}_v = \langle g_v(u_0, v_0), h_v(u_0, v_0) \rangle = \left\langle \frac{\partial x}{\partial v}(u_0, v_0), \frac{\partial y}{\partial v}(u_0, v_0) \right\rangle$$

- The sides of the parallelogram are  $\Delta u \vec{r}_u$  and  $\Delta v \vec{r}_v$  ← See book for details
- The area of  $R$  is approximately

$$|(\Delta u \vec{r}_u) \times (\Delta v \vec{r}_v)| = |\vec{r}_u \times \vec{r}_v| \Delta u \Delta v$$

The Jacobian

$$\text{where } \vec{r}_u \times \vec{r}_v = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k}$$

How much to scale the area  
of  $S$  to get the area of  $R$

**Definition.** What is the Jacobian of the transformation  $T$  given by  $x = g(u, v)$  and  $y = h(u, v)$ ?

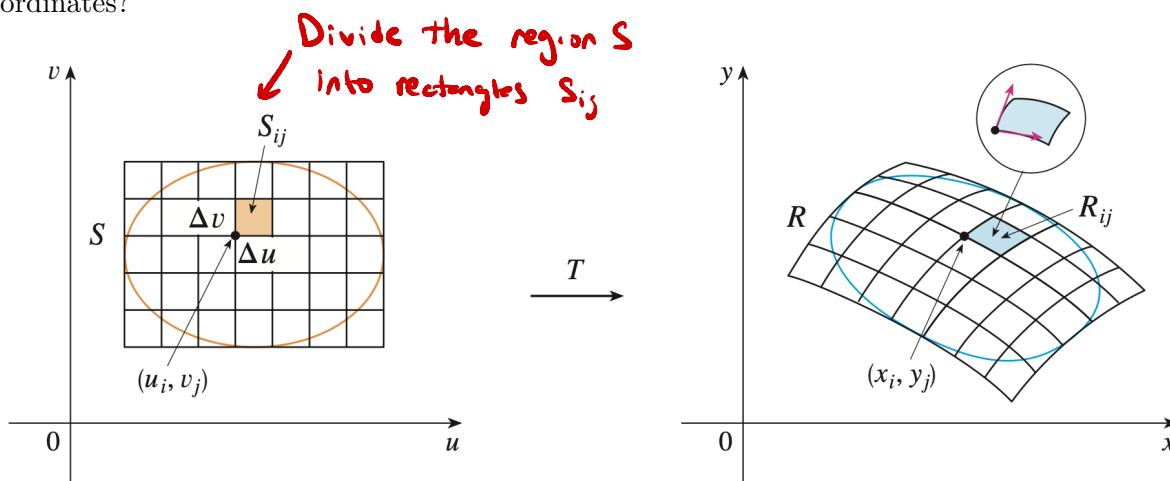
$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

**Remark.** Use the Jacobian to give an approximation to the area  $\Delta A$  of the region  $R$  above.

absolute value

$$\Delta A \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$$

**Theorem.** How can we compute the double integral of  $f$  over  $R$  using a general change of coordinates?



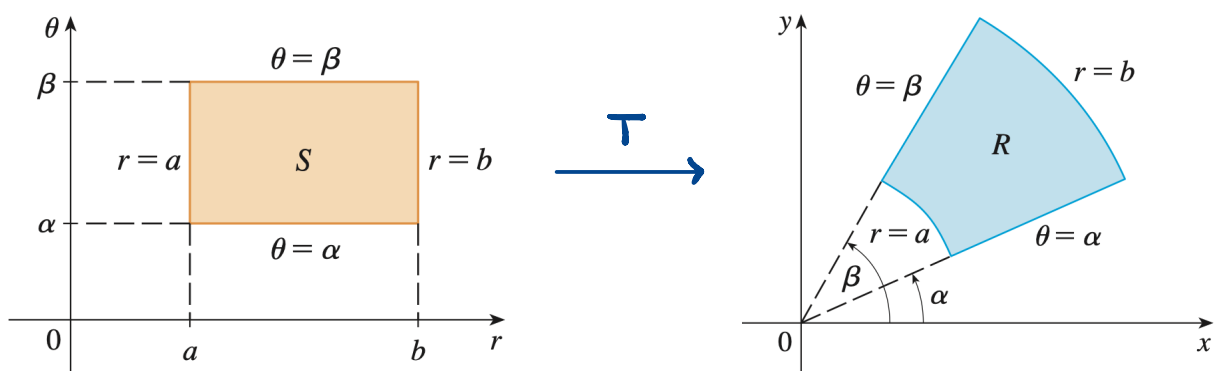
$$\iint_R f(x, y) dA \approx \sum_{i=1}^m \sum_{j=1}^n f(x_i, y_j) \Delta A$$

$$\approx \sum_{i=1}^m \sum_{j=1}^n f(g(u_i, v_j), h(u_i, v_j)) \cdot \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$$

$$\approx \iint_S f(g(u, v), h(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$



**Example.** Show that integration in polar coordinates is just a special case of the change of coordinates formula above.



The transformation  $T$  goes from the  $r\theta$ -plane to the  $xy$ -plane

$$x = g(r, \theta) = r \cos \theta$$

$$y = h(r, \theta) = r \sin \theta$$

The Jacobian is

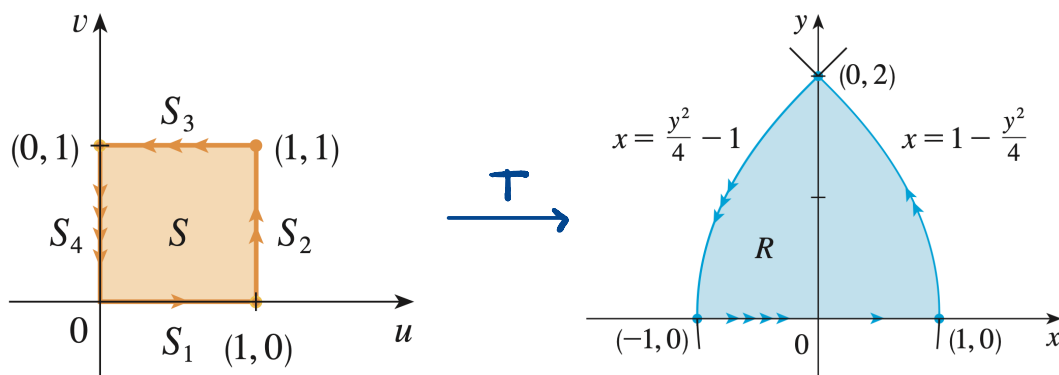
$$\frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r$$

Note:  $r \geq 0$

So...

$$\begin{aligned} \iint_R f(x, y) \, dx \, dy &= \iint_S f(r \cos \theta, r \sin \theta) \left| \frac{\partial(x, y)}{\partial(r, \theta)} \right| \, dr \, d\theta \\ &= \iint_S f(r \cos \theta, r \sin \theta) \cdot r \, dr \, d\theta \end{aligned}$$

**Example.** Use the change of variables  $x = u^2 - v^2$ ,  $y = 2uv$  to evaluate the integral  $\iint_R y \, dA$ , where  $R$  is the region bounded by the  $x$ -axis and the parabolas  $y^2 = 4 - 4x$  and  $y^2 = 4 + 4x$ ,  $y \geq 0$ .

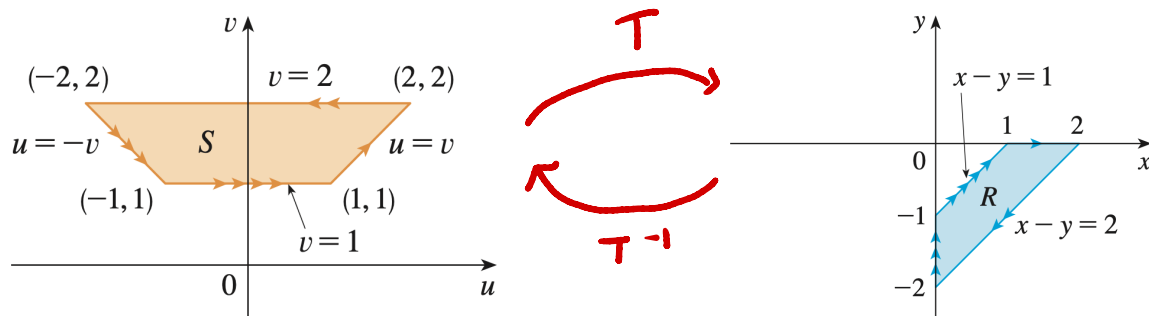


- This is the transformation from the example on pg. 2
- The Jacobian is

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} 2u & -2v \\ 2v & 2u \end{vmatrix} \quad \text{Note: this is } \geq 0 \quad = 4u^2 + 4v^2$$

$$\begin{aligned} \iint_R y \, dA &= \iint_S 2uv \left| \frac{\partial(x,y)}{\partial(u,v)} \right| \, dA = \int_0^1 \int_0^1 2uv \cdot 4(u^2 + v^2) \, du \, dv \\ &= 8 \int_0^1 \int_0^1 u^3 v + uv^3 \, du \, dv \\ &= 8 \int_0^1 \left[ \frac{1}{4} u^4 v + \frac{1}{2} u^2 v^3 \right]_{u=0}^{u=1} \, dv \\ &= \int_0^1 2v + 4v^3 \, dv = \left[ v^2 + v^4 \right]_{v=0}^{v=1} = 2 \end{aligned}$$

**Example.** Evaluate the integral  $\iint_R e^{(x+y)/(x-y)} dA$ , where  $R$  is the trapezoidal region with vertices  $(1, 0)$ ,  $(2, 0)$ ,  $(0, -2)$ , and  $(0, -1)$ .



What should the change of variables be?

$$e^{\frac{x+y}{x-y}}$$

$\xrightarrow{u}$   
 $\xrightarrow{v}$

$$u = x + y \quad \text{and} \quad v = x - y$$

$$\Rightarrow u + v = 2x \quad \text{and} \quad u - v = 2y$$

$$\Rightarrow x = \frac{1}{2}(u + v) \quad \text{and} \quad y = \frac{1}{2}(u - v)$$

Jacobian:

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{vmatrix} = -\frac{1}{2}$$

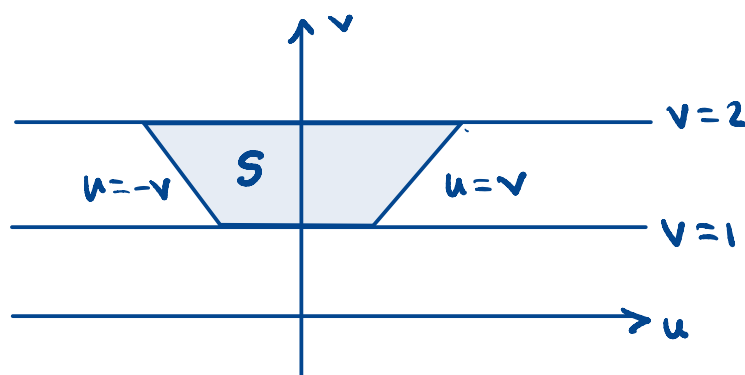
This is negative because going counterclockwise around  $S$  corresponds to going clockwise around  $R$ , so the orientation changes.

What is  $S$ ? The sides of  $R$  are

$$y=0 \quad x-y=2 \quad x=0 \quad x-y=1$$

In the  $uv$ -plane, these lines correspond to

$$u=v \quad v=2 \quad u=-v \quad v=1$$



$\Rightarrow S$  is the trapezoidal region with vertices  $(1,1)$ ,  $(2,2)$ ,  $(-2,2)$ , and  $(-1,1)$

$$\begin{aligned} \iint_R e^{\frac{x+y}{x-y}} dA &= \iint_S e^{u/v} \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv \\ &= \int_1^2 \int_{-v}^v e^{u/v} \cdot \frac{1}{2} du dv = \frac{1}{2} \int_1^2 \left[ v e^{u/v} \right]_{u=-v}^{u=v} dv \\ &= \frac{1}{2} \int_1^2 (e - e^{-1}) v dv \\ &= \frac{3}{4} (e - e^{-1}) \end{aligned}$$

**Theorem.** What is the change of variables formula for triple integrals?

Let  $T$  be a transformation that maps a region  $S$  in  $uvw$ -space onto a region  $R$  in  $xyz$ -space by

$$x = g(u, v, w) \quad y = h(u, v, w) \quad z = k(u, v, w)$$

The Jacobian of  $T$  is the following  $3 \times 3$  determinant

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

We then have

$$\iiint_R f(x, y, z) \, dV = \iiint_S f(g(u, v, w), h(u, v, w), k(u, v, w)) \cdot \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| \, du \, dv \, dw$$

**Example.** Derive the formula for triple integration in spherical coordinates.

$$x = \rho \sin \phi \cos \theta \quad y = \rho \sin \phi \sin \theta \quad z = \rho \cos \phi$$

$$\frac{\partial(x,y,z)}{\partial(\rho,\theta,\phi)} = \begin{vmatrix} \sin \phi \cos \theta & -\rho \sin \phi \sin \theta & \rho \cos \phi \cos \theta \\ \sin \phi \sin \theta & \rho \sin \phi \cos \theta & \rho \cos \phi \sin \theta \\ \cos \phi & 0 & -\rho \sin \phi \end{vmatrix}$$

Expand along  
the bottom row

$$\downarrow = \cos \phi \begin{vmatrix} -\rho \sin \phi \sin \theta & \rho \cos \phi \cos \theta \\ \rho \sin \phi \cos \theta & \rho \cos \phi \sin \theta \end{vmatrix} - \rho \sin \phi \begin{vmatrix} \sin \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \sin \phi \sin \theta & \rho \sin \phi \cos \theta \end{vmatrix}$$

$$= \cos \phi \left( -\rho^2 \sin \phi \cos \phi \sin^2 \theta - \rho^2 \sin \phi \cos \phi \cos^2 \theta \right) - \rho \sin \phi \left( \rho \sin^2 \phi \cos^2 \theta + \rho \sin^2 \phi \sin^2 \theta \right)$$

use the fact  
that  
 $\cos^2 \theta + \sin^2 \theta = 1$

$$= -\rho^2 \sin \phi \cos^2 \phi - \rho^2 \sin \phi \sin^2 \phi = -\rho^2 \sin \phi$$

Since  $0 \leq \phi \leq \pi$ , we have  $\sin \phi \geq 0$ , so  $\left| \frac{\partial(x,y,z)}{\partial(\rho,\theta,\phi)} \right| = \boxed{\rho^2 \sin \phi}$

