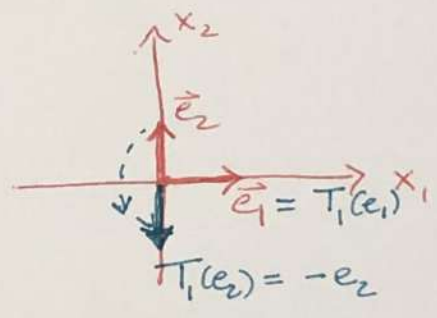


HW 4

Sec. 1.9

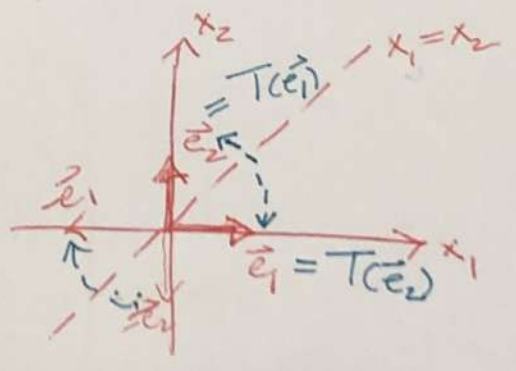
⑧ I'm going to write the two operations separately, then compose them:

$T_1: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
reflection about
 x_1 -axis



followed by T_2

$T_2: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
reflection about
 $x_1 = x_2$



Then, $T = T_2 \circ T_1$, if $T(e_1) = T_2(T_1(e_1)) = T_2(e_1) = e_2$
 $T(e_2) = T_2(T_1(e_2)) = T_2(-e_2) = -e_1$

Therefore,

$$\begin{aligned}
T(\vec{x}) &= T(x\vec{e}_1 + y\vec{e}_2) \\
&= T(x\vec{e}_1) + y T(\vec{e}_2) \\
&= x T(\vec{e}_1) + y T(\vec{e}_2) \\
&= x\vec{e}_2 - y\vec{e}_1 \\
&= \begin{pmatrix} -y \\ x \end{pmatrix} \\
&= \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}
\end{aligned}$$

$$\Rightarrow [T]_{\sigma} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

~~16~~ $\begin{pmatrix} x_1 - x_2 \\ -2x_1 + x_2 \\ x_1 \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} + x_2 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$

~~20~~ $[T]_{\sigma} = \begin{pmatrix} 1 & -1 \\ -2 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

~~$[T]_{\sigma} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -6 \end{pmatrix}$~~

ignore

(12) Since $[T]_{\sigma} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} \cos \pi/2 & -\sin \pi/2 \\ \sin \pi/2 & \cos \pi/2 \end{pmatrix}$
 $= R_{\pi/2}$

we are done.

(18) Write in terms of columns:

$$T \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2x_2 - 3x_1 \\ x_1 - 4x_2 \\ 0 \\ x_2 \end{pmatrix}$$

$$= x_1 \begin{pmatrix} -3 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 2 \\ -4 \\ 0 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} -3 & 2 \\ 1 & -4 \\ 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$= [T]_{\sigma}$$

Since $T(\vec{x}) = [T]_{\sigma} \vec{x}$, it's clear that T is linear.

Sec. 2.1

⑥, Only AB is defined, &

$$AB = \begin{pmatrix} 4 & -2 \\ -3 & 0 \\ 3 & 5 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 2 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} \vec{A}_1 \cdot \vec{b}_1 & \vec{A}_1 \cdot \vec{b}_2 \\ \vec{A}_2 \cdot \vec{b}_1 & \vec{A}_2 \cdot \vec{b}_2 \\ \vec{A}_3 \cdot \vec{b}_1 & \vec{A}_3 \cdot \vec{b}_2 \end{pmatrix}$$

$$= \boxed{\begin{pmatrix} 0 & 14 \\ -3 & -9 \\ 13 & 4 \end{pmatrix}}$$

} for part (b)

or

$$AB = (A\vec{b}_1 \quad A\vec{b}_2)$$

$$= \left((b_{11}\vec{a}_1 + b_{21}\vec{a}_2) \quad (b_{12}\vec{a}_1 + b_{22}\vec{a}_2) \right)$$

$$= \left(\left(1 \begin{pmatrix} 4 \\ -3 \\ 3 \end{pmatrix} + 2 \begin{pmatrix} -2 \\ 0 \\ 5 \end{pmatrix} \right) \quad \left(3 \begin{pmatrix} 4 \\ -3 \\ 3 \end{pmatrix} - 1 \begin{pmatrix} -2 \\ 0 \\ 5 \end{pmatrix} \right) \right)$$

$$= \begin{pmatrix} 4-4 & 12+2 \\ -3+0 & -9+0 \\ 3+10 & 9-5 \end{pmatrix} = \boxed{\begin{pmatrix} 0 & 14 \\ -3 & -9 \\ 13 & 4 \end{pmatrix}}$$

} for part (a)

⑩ $AB = \begin{pmatrix} 2 & -3 \\ -4 & 6 \end{pmatrix} \begin{pmatrix} 8 & 4 \\ 5 & 5 \end{pmatrix} = \begin{pmatrix} 1 & -7 \\ -2 & 14 \end{pmatrix}$

$$AC = \begin{pmatrix} 2 & -3 \\ -4 & 6 \end{pmatrix} \begin{pmatrix} 5 & -2 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 1 & -7 \\ -2 & 14 \end{pmatrix} \checkmark$$

so yet, $AB = AC$, yet $B \neq C$.

Sec. 2.2

④ $\begin{pmatrix} 3 & -4 \\ 7 & -8 \end{pmatrix}^{-1} = \frac{1}{-24+28} \begin{pmatrix} -8 & 4 \\ -7 & 3 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} -8 & 4 \\ -7 & 3 \end{pmatrix}$

$$= \begin{pmatrix} -2 & 1 \\ -7/4 & 3/4 \end{pmatrix}$$

⑭ If D is invertible, we can right-multiply by D^{-1} both sides of $(B-C)D=0$:

$$0 = \underbrace{0D^{-1}}_{\text{why?}} = ((B-C)D)D^{-1}$$

$$= (B-C)(DD^{-1}) \quad (\text{associativity})$$

$$= (B-C)I$$

$$= B-C \quad \leftarrow \text{add } C \text{ to both sides} \Rightarrow B=C.$$

(13) P invertible & $A = PBP^{-1}$

$$\Rightarrow AP = PB$$

(right multiplying both sides by P , & using associativity & $(PB)I = PB$)

$$\Rightarrow P^{-1}AP = B$$

(left multiplying both sides by P^{-1} + associativity & identity).

Sec. 2.3

(8) Invertible $\text{lin. } A\vec{x} = \vec{0} \Rightarrow \vec{x} = \vec{0}$ (use back-substitution) $\Rightarrow N(A) = \{\vec{0}\}$,
& moreover A is square 4×4 .

(16) No, since $R(A) = \text{span}(\vec{a}_1, \dots, \vec{a}_5) \subsetneq \mathbb{R}^5$,
which means A is not onto.

Or for any of the other equivalent reasons.