

# Math 2130 - Practice Final

December 6-8, 2021

(1) Let  $B = \left( \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right)$ .

(a) Why is  $B$  a basis of  $\mathbb{R}^2$ ?

(b) Give change of coordinates matrices  $P_{E \leftarrow B}$  (for changing  $B$ -coordinates into coordinates w.r.t. the standard basis  $E$ ) and  $P_{B \leftarrow E}$ .

(c) Compute the coordinates  $[x]_B$  for  $x = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ .

(2) Let  $B = (b_1, b_2)$  as in the previous problem. Let  $h: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be linear such that  $[h(b_1)]_E = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ ,  $[h(b_2)]_E = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ .

(a) Give the standard matrix  $T_{E \leftarrow E}$  of  $h$  w.r.t. the standard basis.

(b) Compute  $h\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right)$ .

(3) Let

$$A = \begin{bmatrix} 1 & -2 & 3 \\ -2 & 0 & 1 \\ 3 & -2 & 2 \end{bmatrix}$$

(a) Is the mapping  $h: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ ,  $x \mapsto Ax$ , injective, surjective, bijective?

(b) Give bases for null space, row space, column space of  $A$ .

(4) Let  $A$  be the standard matrix for the rotation  $r$  of  $\mathbb{R}^2$  by angle  $\varphi$  counterclockwise around the origin. What are the eigenvalues and eigenvectors of  $A$ ? Can  $A$  be diagonalized over the reals?

(5) Diagonalize  $A$  if possible. Also compute  $\det A$ . Is  $A$  invertible?

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 0 & 3 \\ 0 & 0 & -2 \end{bmatrix}$$

(6) Compute the inverse if possible:

$$A = \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

(7) Let  $h: V \rightarrow W$  be a linear map, let  $v_1, \dots, v_k \in V$  such that  $h(v_1), \dots, h(v_k)$  are linearly independent. Show that  $v_1, \dots, v_k$  are linearly independent.