

# Math 2130 - Assignment 7

Due October 15, 2021

- (1) Explain why the following are not subspaces of  $\mathbb{R}^2$ . Give explicit counter examples for subspace properties that are not satisfied.

(a)  $U = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid x, y \in \mathbb{R}, x \geq 0 \right\}$

(b)  $V = \mathbb{Z}^2$  ( $\mathbb{Z}$  denotes the set of all integers)

(c)  $W = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid x, y \in \mathbb{R}, |x| = |y| \right\}$

**Solution:**

(a) Not closed under scalar multiples, e.g.  $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \in U$  but  $(-1) \begin{bmatrix} 1 \\ 0 \end{bmatrix} \notin U$

(b) Not closed under scalar multiples, e.g.  $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \in V$  but  $\sqrt{2} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \notin V$

(c) Not closed under addition, e.g.  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \in W$  but  $\begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \end{bmatrix} \notin W$

□

- (2) Which of the following are subspaces of the vector space  $\mathbb{R}^{\mathbb{R}} = \{f: \mathbb{R} \rightarrow \mathbb{R}\}$  of all functions from  $\mathbb{R}$  to  $\mathbb{R}$ ? Check all subspace properties or give one that is not satisfied.

(a)  $\{f: \mathbb{R} \rightarrow \mathbb{R} \mid f(0) = 1\}$

(b)  $\{f: \mathbb{R} \rightarrow \mathbb{R} \mid f(3) = 0\}$

(c)  $\{f: \mathbb{R} \rightarrow \mathbb{R} \mid f \text{ is continuous}\}$

**Solution:**

(a) No subspace since it does not contain the zero vector, i.e., the constant 0-function.

(b) Subspace since (1) contains the constant 0-function, (2) is closed under addition [for functions  $f, g$  with  $f(1) = 0$  and  $g(1) = 0$ , also  $(f+g)(1) = 0+0 = 0$ ], (3) is closed under scalar multiples [if  $c \in \mathbb{R}$  and  $f(1) = 0$ , then also  $(cf)(1) = c \cdot 0 = 0$ ].

(c) Subspace since (1) the constant 0-function is continuous, (2) the sum of continuous functions is continuous, (3) any scalar multiple of a continuous function is continuous.

□

- (3) Let  $\mathbf{v}_1, \dots, \mathbf{v}_n$  be vectors in a vector space  $V$ . Show that  $U := \text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  is a subspace of  $V$ .

**Solution:**

We show the 3 conditions for being a subspace.

(a) The zero vector can be written as linear combination  $\mathbf{0} = 0\mathbf{v}_1 + \dots + 0\mathbf{v}_n$ . Thus  $\mathbf{0} \in U$ .

(b) Let  $\mathbf{u}$  and  $\mathbf{w}$  be arbitrary vectors in  $U$ . We can write these vectors as

$$\begin{aligned}\mathbf{u} &= a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n \quad \text{for some } a_1, \dots, a_n \in \mathbb{R}, \\ \mathbf{w} &= b_1\mathbf{v}_1 + \dots + b_n\mathbf{v}_n \quad \text{for some } b_1, \dots, b_n \in \mathbb{R}.\end{aligned}$$

Now

$$\begin{aligned}\mathbf{u} + \mathbf{w} &= a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n + b_1\mathbf{v}_1 + \dots + b_n\mathbf{v}_n \\ &= (a_1 + b_1)\mathbf{v}_1 + \dots + (a_n + b_n)\mathbf{v}_n.\end{aligned}$$

Thus  $\mathbf{u} + \mathbf{w}$  is spanned by  $\mathbf{v}_1, \dots, \mathbf{v}_n$  and hence an element of  $U$ .

(c) Let  $\mathbf{u} \in U$  as above, and let  $r \in \mathbb{R}$ . Then

$$\begin{aligned}r\mathbf{u} &= r(a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n) \\ &= ra_1\mathbf{v}_1 + \dots + ra_n\mathbf{v}_n.\end{aligned}$$

Thus  $r\mathbf{u}$  is spanned by  $\mathbf{v}_1, \dots, \mathbf{v}_n$  and hence an element of  $U$ . □

(4) Let  $A \in \mathbb{R}^{m \times n}$ . Prove that  $\text{Nul}(A)$  is a subspace of  $\mathbb{R}^n$ .

**Solution:**

We show the 3 conditions for being a subspace.

(a) The zero vector is clearly in  $\text{Nul}(A)$  since  $A\mathbf{0} = \mathbf{0}$ .

(b) Let  $\mathbf{u}$  and  $\mathbf{w}$  be arbitrary vectors in  $\text{Nul}(A)$ . Then  $A\mathbf{u} = \mathbf{0}$  and  $A\mathbf{w} = \mathbf{0}$ . We show that  $\mathbf{u} + \mathbf{w}$  is in  $\text{Nul}(A)$ .

$$A(\mathbf{u} + \mathbf{w}) = A\mathbf{u} + A\mathbf{w} = \mathbf{0} + \mathbf{0} = \mathbf{0}.$$

So  $\mathbf{u} + \mathbf{w}$  is in  $\text{Nul}(A)$ .

(c) Let  $r \in \mathbb{R}$ . Then

$$A(r\mathbf{u}) = r(A\mathbf{u}) = r\mathbf{0} = \mathbf{0}.$$

Hence  $r\mathbf{u}$  is in  $\text{Nul}(A)$ . □

(5) Explain whether the following are true or false (give counter examples if possible):

(a) Every vector space is a subspace of itself.

(b) Each plane in  $\mathbb{R}^3$  is a subspace.

(c) Let  $U$  be a subspace of a vector space  $V$ . Any linear combination of vectors of  $U$  is also in  $V$ .

(d) Let  $v_1, \dots, v_n$  be in a vector space  $V$ . Then  $\text{Span}(v_1, \dots, v_n)$  is the smallest subspace of  $V$  containing  $v_1, \dots, v_n$ .

**Solution:**

(a) True, since it contains zero vector, is closed under addition and scalar multiples.

(b) False, e.g., the plane  $z = 1$  does not contain the zero vector.

(c) True, since  $U$  is closed under addition and scalar multiples by definition,  $U$  is also closed under linear combinations.

(d) True, by (c) every subspace of  $V$  containing  $v_1, \dots, v_n$  also contains  $\text{Span}(v_1, \dots, v_n)$  which is a subspace by a previous HW-problem. So  $\text{Span}(v_1, \dots, v_n)$  is the smallest subspace of  $V$  containing  $v_1, \dots, v_n$ .

□

- (6) Are the vectors  $\mathbf{v}_0 = 1$ ,  $\mathbf{v}_1 = t$ ,  $\mathbf{v}_2 = t^2$  in the vector space  $\mathbb{R}^{\mathbb{R}} := \{f: \mathbb{R} \rightarrow \mathbb{R}\}$  linearly independent?

**Solution:**

Yes, for real numbers  $x_0, x_1, x_2$  the polynomial  $x_0 + x_1t + x_2t^2$  is equal to the constant 0-function iff  $x_0 = x_1 = x_2 = 0$ .

Alternatively, consider the equation

$$x_0 + x_1t + x_2t^2 = 0$$

at distinct values for  $t$ , e.g.,  $t = 0, 1, 2$  to obtain the linear system

$$x_0 + 0x_1 + 0^2x_2 = 0$$

$$x_0 + 1x_1 + 1^2x_2 = 0$$

$$x_0 + 2x_1 + 2^2x_2 = 0$$

This only has the trivial solution  $x_0 = x_1 = x_2 = 0$ . So  $1, t, t^2$  are linearly independent. □

- (7) Which of the following are bases of  $\mathbb{R}^3$ ? Why or why not?

$$A = \left( \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \right), B = \left( \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} \right), C = \left( \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right)$$

**Solution:**

$A$  is not a basis because 2 vectors can at most span a plane but not all of  $\mathbb{R}^3$ .

To check whether  $B$  is a basis we have to see whether it spans  $\mathbb{R}^3$ . Row reduce

$$\begin{bmatrix} 1 & 2 & 0 \\ 2 & 3 & -1 \\ 0 & 4 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

Since we have a 0-row, the vectors in  $B$  do not span  $\mathbb{R}^3$ . Hence  $B$  is not a basis.

To check whether  $C$  is a basis we have to see whether it spans  $\mathbb{R}^3$ . Row reduce

$$\begin{bmatrix} 1 & 2 & 0 \\ 2 & 3 & 1 \\ 0 & 4 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 8 \end{bmatrix}$$

The echelon form has no 0-row. So  $C$  spans  $\mathbb{R}^3$ . Further we see from the echelon form that  $C$  is linearly independent. So  $C$  is a basis. □

- (8) Give a basis for  $\text{Nul}(A)$  and a basis for  $\text{Col}(A)$  for

$$A = \begin{bmatrix} 0 & 2 & 0 & 3 \\ 1 & -4 & -1 & 0 \\ -2 & 6 & 2 & -3 \end{bmatrix}$$

**Solution:**

Nul  $A$  is the solution set of  $Ax = 0$ . So we row reduce  $A$

$$A = \begin{bmatrix} 0 & 2 & 0 & 3 \\ 1 & -4 & -1 & 0 \\ -2 & 6 & 2 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & -4 & -1 & 0 \\ 0 & 2 & 0 & 3 \\ 0 & -2 & 0 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & -4 & -1 & 0 \\ 0 & 2 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

to get the solution  $x_4 = t, x_3 = s$  (both free),  $x_2 = -\frac{3}{2}t, x_1 = s - 6t$ . So

$$x = s \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -6 \\ -\frac{3}{2} \\ 0 \\ 1 \end{bmatrix} \text{ and Nul } A \text{ has basis } \left( \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -6 \\ -\frac{3}{2} \\ 0 \\ 1 \end{bmatrix} \right)$$

For a basis of the column space  $\text{Col}A$  we pick the pivot columns of  $A$ , i.e., the first

and second column. So  $\text{Col}A$  has basis  $\left( \begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 2 \\ -4 \\ 6 \end{bmatrix} \right)$ . □