Math 3130 - Assignment 9

Due March 18, 2016 Markus Steindl

- (73) [1, Section 4.2] Let $T: \mathbb{P}_3 \to \mathbb{R}, p \mapsto p(3)$, be the map that evaluates a polynomial p at x = 3.
 - (a) Show that T is linear.
 - (b) Determine the kernel and the range of T.
 - (c) Is T injective, surjective, bijective?

Solution:

(a) For linearity, let $p, q \in \mathbb{P}_3$. Their sum p + q is the polynomial that maps t to p(t) + q(t). So

$$T(p+q) = (p+q)(3) = p(3) + q(3) = T(p) + T(q).$$

Further let $c \in \mathbb{R}$. Then cp maps t to cp(t). So

$$T(cp) = (cp)(3) = cp(3) = cT(p).$$

Hence T is linear.

(b) The kernel of T, ker T, consists of all the polynomials that evaluate to 0 at 3, that is,

$$\ker T = \{(t-3)q : q \in \mathbb{P}_2\}.$$

The range of T, $T(\mathbb{P}_3)$, is \mathbb{R} . For every $b \in \mathbb{R}$, there exists a polynomial $p \in \mathbb{P}_3$ that is mapped to b. Choose for example the constant polynomial p(t) = b.

(c) Since the kernel of T is non-trivial, T is not injective. Since the range of T is equal to its codomain, T is surjective. T is not bijective since it is not injective.

(74) [1, Section 4.4]

(a) Let $B = \begin{pmatrix} 1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$) be a basis of a subspace H of \mathbb{R}^3 . Compute the coordinates $[u]_B$ for $u = \begin{bmatrix} -5 \\ 11 \\ 5 \end{bmatrix}$ in H.

Solution:

Solve the linear system

$$c_1 \begin{bmatrix} 1\\1\\3 \end{bmatrix} + c_2 \begin{bmatrix} 2\\-2\\1 \end{bmatrix} = \begin{bmatrix} -5\\11\\5 \end{bmatrix}$$

to obtain $c_1 = 3, c_2 = -4$. So $[u]_B = \begin{bmatrix} 3\\-4 \end{bmatrix}$.

(b) Let $C = (1 + t, t + t^2, 1 + t^2)$ be a basis for \mathbb{P}_2 . Compute the coordinates $[p]_C$ for $p = 2 + t^2$. Solution:

Solve

 $c_1(1+t) + c_2(t+t^2) + c_3(1+t^2) = 2+t^2.$

Comparing the coefficients on both sides of this equation yields

 $c_1 + c_3 = 2$ (constant part) $c_1 + c_2 = 0$ (multiples of t) $c_2 + c_3 = 1$ (multiples of t^2)

Solving that system of linear equations yields $c_1 = \frac{1}{2}, c_2 = -\frac{1}{2}, c_3 = \frac{3}{2}$. So $[u]_B = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{3}{2} \end{bmatrix}.$

(75) [1, Section 4.6]

(a) If A is a 3×4 -matrix, what is the largest possible rank of A? What is the smallest possible dimension of Nul A?

Solution:

The rank of a matrix is the number of its pivot elements, which is at most the number of its rows and at most the number of its columns. So rank $A \leq$ $\max(3,4) = 3$. Since the largest possible rank is 3, the smallest number of free variables in Ax = 0 is 1. So the dimension of Nul A is 1 or larger.

(b) If the nullspace of a 4×6 -matrix B has dimension 3, what is the dimension of the row space of B? Solution:

dim Nul A + dim Row A = the number of columns of ASo dim Row $A = 6 - \dim \operatorname{Nul} A = 6 - 3 = 3$.

(76) [1, Sections 4.3-4.6] True or false? Explain your answers:

(a) Any plane in \mathbb{R}^3 is isomorphic to \mathbb{R}^2 . Solution:

False. Only planes through the origin are subspaces of \mathbb{R}^3 . They are isomorphic to \mathbb{R}^2 by the coordinate mapping.

(b) A basis for V is a linear independent set that is as large as possible. Solution:

True. If B is a basis and you add another vector v to B, the new set will be linearly independent because v is a linear combination of the vectors in B. On the other hand, assume B is a linearly independent set such that whenever any other vector v is added to B, then the new set is linearly dependent. Then any other vector must be a linear combination of the vectors in B. So B spans V and B is a basis.

(c) If v_1, \ldots, v_k are linearly independent in V, then $k \leq \dim V$.

True. A linear independent set cannot have more elements than a basis of V.

- (d) If B is an echelon form of A, then the pivot columns of B are a basis for Col A.
 Solution:
 False. The pivot columns of A are a basis for Col A.
- (e) The row space of A^T is equal to the column space of A.
 Solution:
 True. Transposing a matrix A changes the columns of A to the rows of A^T. □
- (77) [1, Section 3.1] Compute the determinant of the matrices by cofactor expansion. Pick a row or column that yields the least amount of computation:

$$A = \begin{bmatrix} 0 & 1 & -3\\ 5 & 4 & -4\\ 0 & -3 & -4 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 0 & -3 & 0\\ 3 & 1 & 5 & 1\\ 2 & 0 & 0 & 0\\ 7 & 1 & -2 & 5 \end{bmatrix}$$

Solution:

Expand $\det A$ down the first column:

 $\det A = 0 \cdot \det A_{11} - 5 \cdot \det A_{21} + 0 \cdot \det A_{31} = -5 \cdot \det \begin{bmatrix} 1 & -3 \\ -3 & -4 \end{bmatrix} = -5(1(-4) - (-3)(-3)) = 65$

Expand det B across 3rd row:

$$\det B = 2 \cdot \det B_{13} = 2 \cdot \det \begin{bmatrix} 0 & -3 & 0 \\ 1 & 5 & 1 \\ 1 & -2 & 5 \end{bmatrix}$$

Expand across 1st row:

det
$$B_{13} = -1(-3)$$
 det $\begin{bmatrix} 1 & 1 \\ 1 & 5 \end{bmatrix} = 3 \cdot (1 \cdot 5 - 1 \cdot 1) = 12$

So det $B = 2 \cdot 12 = 24$.

(78) [1, Section 3.1] Rule of Sarrus for the determinant of 3×3 -matrices. Let

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Prove that

det
$$A = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}$$

Hint: Expand det A across the first row.

Solution:

$$\det A = a_{11} \cdot \det A_{11} - a_{12} \cdot \det A_{12} + a_{13} \cdot \det A_{13}$$

= $a_{11} \cdot \det \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12} \cdot \det \begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13} \cdot \det \begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}$
= $a_{11}(a_{22}a_{33} - a_{23}a_{32}) - a_{12}(a_{21}a_{33} - a_{23}a_{31}) + a_{13}(a_{21}a_{32} - a_{22}a_{31})$
= $a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}$

(79) [1, Section 3.1] Give two 3×3-matrices with determinat 5. (Hint: triangular matrices.) Solution:

Any triangular or diagonal matrix whose diagonal elements multiply to 5 will do, e.g.,

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

(80) [1, Section 3.2] Compute the determinants by row reduction to echelon form:

$$A = \begin{bmatrix} 3 & 3 & -3 \\ 3 & 4 & -4 \\ 2 & -3 & -5 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 2 & 7 & 6 & -3 \\ -3 & -10 & -7 & 2 \end{bmatrix}$$

Solution:

$$\det A = 3 \cdot \det \begin{bmatrix} 1 & 1 & -1 \\ 3 & 4 & -4 \\ 2 & -3 & -5 \end{bmatrix} \quad \text{factoring 3 from the first row}$$
$$= 3 \cdot \det \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & -1 \\ 0 & -5 & -3 \end{bmatrix} \quad \text{subtracting multiples of the first row from the others}$$
$$= 3 \cdot \det \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -8 \end{bmatrix} \quad \text{adding 5 times the second row to the third}$$
$$= 3 \cdot 1 \cdot 1 \cdot (-8) = -24.$$

$$\det B = \det \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 0 & 1 & 2 & 5 \\ 0 & -1 & -1 & -10 \end{bmatrix}$$
$$= \det \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 0 & 0 & 0 & 10 \\ 0 & 0 & 1 & -15 \end{bmatrix}$$
$$= -\det \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 0 & 0 & 1 & -15 \\ 0 & 0 & 1 & -15 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$
flipped row 3 and 4
$$= -1 \cdot 1 \cdot 1 \cdot 10 = -10.$$

(81) [1, Section 3.2] Consider $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$.

(a) How does switching the rows effect the determinant? Compare det A and det $\begin{bmatrix} c & d \\ a & b \end{bmatrix}$.

Solution:

Interchanging 2 rows changes the sign of the determinant:

$$\det \begin{bmatrix} c & d \\ a & b \end{bmatrix} = cb - ad = -\det A$$

(b) How does adding a multiple of one row to the other row effect the determinant? Compare det A and det $\begin{bmatrix} a & b \\ c+ra & d+rb \end{bmatrix}$. Solution:

Adding a multiple of the first row to another does not change the determinant:

$$\det \begin{bmatrix} a & b \\ c+ra & d+rb \end{bmatrix} = a(d+rb) - b(c+ra) = ad - bc = \det A$$

References

[1] David C. Lay. Linear Algebra and Its Applications. Addison-Wesley, 4th edition, 2012.