

**3.1. Determining the Jordan form.** It is easy to determine the Jordan form of a matrix, provided one knows the eigenvalues. One can also use this to establish the uniqueness of the Jordan form, up to permuting the blocks.

**Theorem 9.3.8** (Computing Jordan forms). *Let  $A \in M_n(K)$ , let  $\lambda_1, \dots, \lambda_m \in \overline{K}$  ( $m \leq n$ ) be the distinct eigenvalues of  $A$ , and assume that all the eigenvalues of  $A$  lie in  $K$ . For  $i = 1, \dots, m$ , let*

$$\begin{aligned} T_{\lambda_i} &:= A - \lambda_i I, \\ d_{\lambda_i}^{(j)} &:= \dim \ker T_{\lambda_i}^j. \end{aligned}$$

Then we have that

$$d_{\lambda_i}^{(j)} = \sum_{\ell=1}^j \#\{\text{Jordan blocks for } \lambda_i \text{ of size at least } \ell\}.$$

PROOF. We leave the proof of the theorem as an exercise.  $\square$

REMARK 9.3.9. From the theorem we have,

$$\begin{aligned} d_{\lambda_i}^{(1)} &= \#\{\text{Jordan blocks for } \lambda_i\} \\ d_{\lambda_i}^{(2)} - d_{\lambda_i}^{(1)} &= \#\{\text{Jordan blocks for } \lambda_i \text{ of size at least } 2\} \\ &\vdots \\ d_{\lambda_i}^{(j)} - d_{\lambda_i}^{(j-1)} &= \#\{\text{Jordan blocks for } \lambda_i \text{ of size at least } j\}. \end{aligned}$$

Moreover, if  $d_{\lambda_i}^{(j)} = d_{\lambda_i}^{(j+1)}$ , then  $d_{\lambda_i}^{(j)} = d_{\lambda_i}^{(j+k)}$  for all  $k \geq 1$ .

REMARK 9.3.10. Knowing the multiplicities of the eigenvalues as roots of the characteristic polynomial, one can reduce the amount of computation needed to find the Jordan form. For instance, if  $\lambda_i$  has multiplicity  $m_i$  as a root of the characteristic polynomial, then there can be at most  $m_i$  Jordan blocks for  $\lambda_i$ , with equality holding if and only if each Jordan block is size 1. Similarly, the maximum size of a Jordan block for  $\lambda_i$  is  $m_i$ , with equality holding if and only if there is only one Jordan block for  $\lambda_i$ .

**Example 9.3.11.** Let us compute a Jordan form for the matrix

$$A = \begin{bmatrix} 1 & 2 & 4 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

using the algorithm above; there are faster methods, but this will illustrate the general algorithm. First, we find the characteristic polynomial

$$p_A(t) = (1-t)(2-t)(2-t),$$

so that the eigenvalues of  $A$  are  $\lambda_1 = 1$  and  $\lambda_2 = 2$ . We then start computing the  $d_{\lambda_i}^{(j)}$ .

$$d_{\lambda_1}^{(1)} = \dim \ker(A - I) = \dim \ker \begin{bmatrix} 0 & 2 & 4 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \dim \ker \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = 1.$$

The matrix computation was to reduce to row echelon form, from which it is easy to compute the dimension of the kernel. Similarly, one can compute

$$d_{\lambda_1}^{(2)} = \dim \ker(A - I)^2 = 1, \quad d_{\lambda_1}^{(3)} = \dim \ker(A - I)^3 = 1.$$

Thus there is one Jordan block for the eigenvalue 1, and this Jordan block is of size 1.

Next we compute:

$$d_{\lambda_2}^{(1)} = \dim \ker(A - 2I) = \dim \ker \begin{bmatrix} -1 & 2 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = 1.$$

$$d_{\lambda_2}^{(2)} = \dim \ker(A - 2I)^2 = 2.$$

$$d_{\lambda_2}^{(3)} = \dim \ker(A - 2I)^3 = 2.$$

Thus we conclude that there is 1 Jordan block for the eigenvalue 2, and this Jordan block is size 2. In short, we have that a Jordan form for  $A$  is given by

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 2 \end{bmatrix}.$$

Of course, we could have deduced this immediately from the fact that 2 is a root of multiplicity 2 for the characteristic polynomial, and that  $\dim \ker(A - 2I) = 1$ .