Constraint Satisfaction Problems A Survey

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Algebra & Algorithms University of Colorado May 19, 2016 CSP = specifications of subpowers of a finite algebra

Fix a finite algebra **A**.

Definition

- A constraint network over **A** is a pair (n, φ) where
 - ▶ n ≥ 1

• φ is a quantifier-free formula of the form $\bigwedge_{i \in I} R_i(\mathbf{x}_i)$, where for each $i \in I$,

- \mathbf{x}_i is a *d*-tuple of variables from $\{x_1, \ldots, x_n\}$ (for some *d*)
- R_i is a **subuniverse** of \mathbf{A}^d .

The relation **defined by** (n, φ) is

$$\operatorname{Rel}_{\mathbf{A}}(n,\varphi) = \{ \mathbf{a} \in A^n : \varphi(\mathbf{a}) \}.$$

Example

L

$$A = (\{0,1\}; x+y+z)$$

$$R_0 = \{(0,0,0), (0,1,1), (1,0,1), (1,1,0)\}$$

$$R_1 = \{(0,0,1), (0,1,0), (1,0,0), (1,1,1)\}.$$

 $R_0, R_1 \leq \mathbf{A}^3$. Thus the following is a constraint network over \mathbf{A} :

$$(6, \underbrace{R_0(x_1, x_2, x_3) \land R_1(x_1, x_4, x_5) \land R_0(x_2, x_4, x_6) \land R_1(x_3, x_5, x_6)}_{\varphi}).$$

We can view φ as asserting (over \mathbb{Z}_2)

$$\begin{array}{rcl} x_1 + x_2 + x_3 & = & 0 \\ x_1 & + x_4 + x_5 & = & 1 \\ x_2 & + x_4 & + x_6 & = & 0 \\ & + x_3 & + x_5 + x_6 & = & 1. \end{array}$$

 $\operatorname{Rel}_{\mathbf{A}}(\mathbf{6},\varphi)$ is the solution-set to this linear system.

Variant notations

A constraint network over **A** is a pair (n, φ) , $\varphi = \bigwedge_i R_i(\mathbf{x}_i) \dots$

| | may be written as |
|-------------------------------------|---|
| п | $\{x_1,\ldots,x_n\}$ (= V, the set of variables) |
| arphi | $\{x_1, \dots, x_n\} \ (=V, \text{ the set of variables})$ $\{(\mathbf{x}_i, R_i) : i \in I\} \ (= \mathcal{C})$ |
| | (x_i, R_i) is called a constraint x_i is its scope R_i is its constraint relation |
| (n, φ) | (V, \mathcal{C}) or (V, A, \mathcal{C}) Sol (V, \mathcal{C}) |
| $\operatorname{Rel}_{A}(n,\varphi)$ | $\mathrm{Sol}(V, \mathcal{C})$ |

Decision Problems

Definition (n, φ) is k-ary if each scope has length $\leq k$.

Definition CSP(\mathbf{A}, k) Input: A *k*-ary constraint network (n, φ) over \mathbf{A} . Question: Is $\operatorname{Rel}_{\mathbf{A}}(n, \varphi) \neq \emptyset$?

Dichotomy Conjecture (Feder & Vardi) For all **A** and k, CSP(**A**, k) is in P or is NP-hard.

Algebraic Dichotomy Conjecture (Bulatov, Krokhin & Jeavons) If **A** has a Taylor operation, then $CSP(\mathbf{A}, k)$ is in P for every k.



Taylor operations

Definition

An operation $t: A^n \to A$ is a **Taylor operation** if

- 1. *t* is idempotent $(t(x, x, \ldots, x) \approx x)$;
- 2. For each i = 1, ..., n, t satisfies an identity of the form $t(\mathbf{x}) \approx t(\mathbf{y})$ with $x_i \neq y_i$.

Theorem (Taylor; Barto & Kozik; Hobby & McKenzie) For a finite algebra **A**, the following are equivalent:

- 1. A has a Taylor (term) operation.
- 2. A satisfies some idempotent Maltsev condition not satisfied by $_{\rm SETS.}$
- 3. A has an idempotent cyclic term $t(x_1, \ldots, x_n)$, i.e.,

$$t(x_1, x_2, \ldots, x_n) \approx t(x_2, \ldots, x_n, x_1).$$

4. $V(\mathbf{A})$ omits type **1**.

Progress

Algebraic Dichotomy Conjecture If **A** has a Taylor operation, then $\underbrace{CSP(\mathbf{A}, k) \text{ is in P for every } k}_{\mathbf{A} \text{ is tractable}}$.

Theorem

A is known to be tractable if:

- 1. $V(\mathbf{A})$ is CM. (Dalmau '05 + IMMVW '07, using Barto '16?)
- 2. $V(\mathbf{A})$ is SD(\wedge). (Barto & Kozik '09; Bulatov '09)
- 3. **A** is Taylor + conservative, i.e. $Su(\mathbf{A}) = \mathcal{P}(A)$. (Bulatov '03)
- 4. A is Taylor and |A| = 2 or 3. (Schaefer '78, Bulatov '02)

Definition

Let **A** be a finite algebra, \mathcal{A} a set of finite algebras.

- 1. $CSP(\mathbf{A}) = \bigcup_k CSP(\mathbf{A}, k)$. "Global"
- 2. $CSP(\mathcal{A}, k) = \bigcup_{\mathbf{A} \in \mathcal{A}} CSP(\mathbf{A}, k)$. "Uniform"

Can't ask these problems to be in P. (Set of inputs is problematic.)

Definition

Say CSP(**A**) [CSP(A, k)] is "in" P if there is a poly-time algorithm which correctly decides all inputs to CSP(**A**) [CSP(A, k)].

Global Tractability Problem

If A is tractable, does it follow that CSP(A) is "in" P?

A is globally tractable

Uniform Tractability Question

(For a given Taylor class \mathcal{A}): Is $CSP(\mathcal{A}, k)$ "in" P for all k?

 ${\mathcal A}$ is uniformly tractable

Theorem

A is known to be globally tractable if:

- 1. A has a cube term. (Dalmau '05 + IMMVW '07)
- 2. $V(\mathbf{A})$ is SD(\wedge). (Bulatov '09; Barto '14)
- 3. A is Taylor + conservative. (Bulatov '03)
- 4. **A** is Taylor and |A| = 2 or 3. (Schaefer '78, Bulatov '02)

Theorem (Bulatov '09; Barto '14)

The class SD_{\wedge} of all finite algebras generating an SD(\wedge) variety is uniformly globally tractable.

Open problems

- 1. If $V(\mathbf{A})$ is congruence modular, is **A** globally tractable?
- 2. Is the class $\mathcal M$ of finite Maltsev algebras uniformly tractable?
- 3. If A has a difference term, is A tractable?
- 4. Suppose ${\bf A}$ is idempotent and has a congruence θ such that
 - ▶ $\mathbf{A}/\theta \in S\mathcal{D}_{\wedge}$, and
 - Each θ -block is in \mathcal{M} .

("SD(\land) over Maltsev.") Is A tractable?

Standard reductions

 $CSP(\mathbf{A}, k)$ reduces to:

- 1. $CSP(\mathbf{A}||_U, k)$, where U is a minimal range of a unary idempotent term, and $\mathbf{A}||_U$ is the induced term-minimal algebra defined on U.
- 2. $CSP((\mathbf{A}||_U)^{id}, k)$ where $(\mathbf{B})^{id}$ is the idempotent reduct of **B**.

(This is the "reduction to the idempotent case.")

- 3. $CSP(\mathbf{A}^{\lceil k/2 \rceil}, 2)$
- multi-CSP(H(A)_{si}, kd), where A is a subdirect product of d subdirectly irreducible homomorphic images.

5.
$$CSP(\mathbf{A}^+, k)$$
 where $\mathbf{A}^+ = (A; Pol(Su(\mathbf{A}^k)))$.

Conditioning the input – local consistency

Let (n, φ) be a 2-ary constraint network over **A**.

At essentially no cost, one can assume that (n, φ) is "determined" by a "(2,3)-minimal" constraint network.

Definition

A 2-ary constraint network (n, φ) is a **(2,3)-system**¹ provided for all $i, j \in \{1, 2, ..., n\}$:

1. φ has exactly one constraint $R_{i,j}(x_i, x_j)$ with scope (x_i, x_j) .

2.
$$R_{j,i} = (R_{i,j})^{-1}$$

3. For all
$$k$$
, $R_{i,j} \subseteq R_{i,k} \circ R_{k,j}$.

The "associated potatoes" are $A_i := \text{proj}_1(R_{i,j}), i = 1, ..., n$.

Fact

There is a poly-time algorithm which, given a 2-ary constraint network over A, outputs an equivalent (2,3)-system over A.

¹There is no standard terminology.

Conditioning the input – absorption

Definition

Suppose **A** is a finite idempotent algebra and $\mathbf{B} \leq \mathbf{A}$.

1. **B** is an **absorbing subalgebra** if there exists a term operation $t(x_1, \ldots, x_m)$ of **A** such that

$$t(B,\ldots,B,A,B,\ldots,B)\subseteq B$$

for all possible positions of A.

2. A is absorption-free if it has no proper absorbing subalgebra.

Given a (2,3)-system (n, φ) over an idempotent **A**, Barto & Kozik show how to "shrink" the associated potatoes to absorption-free algebras, though losing (2,3)-systemhood and equivalency.

In some situations this has proven to be useful.

Miklós magic

Lemma (Maróti '09)

Suppose **A** is idempotent and has a term operation t(x, y) such that:

- 1. $\mathbf{A} \models t(x, t(x, y)) \approx t(x, y)$.
- 2. t(a, x) is non-surjective, for all $a \in A$.
- 3. There exists a proper subalgebra C < A such that if t(x, a) is surjective then $a \in C$.

Then $CSP(\mathbf{A}, k)$ can be reduced to multi- $CSP(\mathcal{B} \setminus {\mathbf{A}}, \ell)$, where

- ▶ 𝔅 is the closure of {**A**} under *H*, *S*, and "idempotent unary polynomial retracts."
- $\blacktriangleright \ \ell = \max(k, |A|).$

This may seem random, but it is useful (and the proof is beautiful).

Moving forward

Suppose (n, φ) is a *k*-ary constraint network over **A**, and $R = \operatorname{Rel}_{\mathbf{A}}(n, \varphi) \leq \mathbf{A}^n$.

Definition

A **compact** *k*-frame for *R* is a subset $F \subseteq R$ such that

1.
$$\operatorname{proj}_J(F) = \operatorname{proj}_J(R)$$
 for all $J \subseteq \{1..., n\}$ with $|J| \le k$.
2. $|F| \le |A|^{k\binom{n}{k}}$.

Every relation definable by a k-ary constraint network over **A** has a compact k-frame, and is determined by any one of its k-frames.

Speculation: Is it possible to mimic the few subpowers algorithm without having few subpowers?

To carry this out, we would need a notion of "compact *k*-representation" extending compact *k*-frames with more data.

The following problem seems central:

Functional Dependency Problem

Suppose

- A is finite, idempotent, Taylor.
- ► F is a compact k-frame for a relation R ≤ Aⁿ defined by some k-ary constraint network over A.

•
$$X \subseteq \{1, \ldots, n\}$$
 and $\ell \in \{1, \ldots, n\} \setminus X$.

What additional data would enable us to efficiently decide whether $\operatorname{proj}_{X \cup \{\ell\}}(R)$ is the graph of a function $f : \operatorname{proj}_X(R) \to \operatorname{proj}_\ell(R)$?

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